# Numerical Methods II 

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## Euler-Maruyama method

For the vector SDE

$$
\mathrm{d} S=a(S, t) \mathrm{d} t+b(S, t) \mathrm{d} W
$$

the Euler-Maruyama approximation is again

$$
\widehat{S}_{n+1}=\widehat{S}_{n}+a\left(\widehat{S}_{n}, t_{n}\right) h+b\left(\widehat{S}_{n}, t_{n}\right) \Delta W_{n}
$$

but now $a(S, t)$ is a vector, $b(S, t)$ is a matrix and $\Delta W_{n}$ is a vector of Brownian increments with a prescribed correlation.

Remember: can define $\Delta W_{n}=L Z_{n}$ where elements of $Z_{n}$ are i.i.d. unit Normals and

$$
L L^{T}=\operatorname{Cov}\left(\Delta W_{n}\right)
$$

## Euler-Maruyama method

Provided $a$ and $b$ are Lipschitz continuous in $S$ :

- $O(h)$ weak convergence
- $O(\sqrt{h})$ strong convergence

Theoretical result (Clark \& Cameron, 1980) proves this is the best strong convergence that can be achieved in the general vector case based solely on Brownian increments $\Delta W_{n}$.

However, can do better in the scalar case, and also in the vector case in special cases or if we have additional information about the driving Brownian motion

## Milstein Method

Start with scalar case:

$$
\mathrm{d} S=a(S, t) \mathrm{d} t+b(S, t) \mathrm{d} W
$$

which corresponds to the integral equation:

$$
S(t)=S(0)+\int_{0}^{t} a(S(t), t) \mathrm{d} t+\int_{0}^{t} b(S(t), t) \mathrm{d} W(t)
$$

where second integral is an Itô integral.
Approximating this on interval $[0, h]$ using

$$
a(S(t), t) \approx a(S(0), 0), \quad b(S(t), t) \approx b(S(0), 0)
$$

gives Euler-Maruyama method.

## Milstein Method

An asymptotic expansion gives

$$
S(t)=S(0)+b(S(0), 0) W(t)+O(h)
$$

and hence

$$
\begin{aligned}
b(S(t), t)) & =b(S(0), 0)+b^{\prime}(S(0), 0)(S(t)-S(0))+O(h) \\
& =b(S(0), 0)+b^{\prime}(S(0), 0) b(S(0), 0) W(t)+O(h)
\end{aligned}
$$

This then leads to
$S(h)=S(0)+a_{0} h+b_{0} W(h)+b_{0}^{\prime} b_{0} \int_{0}^{h} W(t) \mathrm{d} W(t)+O\left(h^{3 / 2}\right)$
where $a_{0}, b_{0}, b_{0}^{\prime}$ are all evaluated at $(S(0), 0)$.

## Milstein Method

With a standard Lebesgue integral we would say

$$
\int_{0}^{h} W(t) \mathrm{d} W(t)=\int_{0}^{h} \mathrm{~d}\left(\frac{1}{2} W^{2}(t)\right)=\frac{1}{2} W^{2}(h)
$$

but that would be wrong here!
Instead we must use Itô calculus to give

$$
\mathrm{d}\left(\frac{1}{2} W^{2}\right)=W(t) \mathrm{d} W(t)+\frac{1}{2} \mathrm{~d} t
$$

and hence

$$
\int_{0}^{h} W(t) \mathrm{d} W(t)=\frac{1}{2}\left(W^{2}(h)-h\right)
$$

## Milstein Method

This then gives us

$$
S(h)=S(0)+a_{0} h+b_{0} W(h)+\frac{1}{2} b_{0}^{\prime} b_{0}\left(W^{2}(h)-h\right)+O\left(h^{3 / 2}\right)
$$

and so the Milstein scheme is

$$
\begin{aligned}
\widehat{S}_{n+1}= & \widehat{S}_{n}+a\left(\widehat{S}_{n}, t_{n}\right) h+b\left(\widehat{S}_{n}, t_{n}\right) \Delta W_{n} \\
& +\frac{1}{2} b^{\prime}\left(\widehat{S}_{n}, t_{n}\right) b\left(\widehat{S}_{n}, t_{n}\right)\left(\Delta W_{n}^{2}-h\right)
\end{aligned}
$$

Note that $\mathbb{E}\left[\Delta W_{n}^{2}-h\right]=0, \quad \mathbb{V}\left[\Delta W_{n}^{2}-h\right]=2 h^{2}$
so the r.m.s. effect of extra "Milstein term" after $T / h$ timesteps is $O(\sqrt{h})$, correcting the $O(\sqrt{h})$ error of the Euler-Maruyama method.

## Strong convergence

Numerical demonstration: Geometric Brownian Motion

$$
\begin{aligned}
& \mathrm{d} S=r S \mathrm{~d} t+\sigma S \mathrm{~d} W \\
& r=0.05, \sigma=0.5, T=1
\end{aligned}
$$

## Strong convergence



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## Strong convergence



## Milstein Method

In the vector case, the SDE

$$
\mathrm{d} S_{i}=a_{i}(S, t) \mathrm{d} t+\sum_{j} b_{i j}(S, t) \mathrm{d} W_{j}
$$

corresponds to the integral equation:

$$
S_{i}(t)=S_{i}(0)+\int_{0}^{t} a_{i}(S(t), t) \mathrm{d} t+\sum_{j} \int_{0}^{t} b_{i j}(S(t), t) \mathrm{d} W_{j}(t)
$$

and the Euler-Maruyama approximation is

$$
\widehat{S}_{i, n+1}=\widehat{S}_{i, n}+a_{i}\left(\widehat{S}_{n}, t_{n}\right) h+\sum_{j} b_{i j}\left(\widehat{S}_{n}, t_{n}\right) \Delta W_{j, n}
$$

## Milstein Method

An asymptotic expansion gives

$$
S_{i}(t) \approx S_{i}(0)+\sum_{j} b_{i j}(S(0), 0) W_{j}(t)
$$

and hence

$$
\begin{aligned}
\left.b_{i j}(S(t), t)\right) & \approx b_{i j}+\sum_{l} \frac{\partial b_{i j}}{\partial S_{l}}\left(S_{l}(t)-S_{l}(0)\right) \\
& \approx b_{i j}+\sum_{k, l} \frac{\partial b_{i j}}{\partial S_{l}} b_{l k} W_{k}(t)
\end{aligned}
$$

with $b$ and its derivatives evaluated at $(S(0), 0)$.

## Milstein Method

This then leads to
$S_{i}(h) \approx S_{i}(0)+a_{i} h+\sum_{j} b_{i j} W_{j}(h)+\sum_{j, k, l} \frac{\partial b_{i j}}{\partial S_{l}} b_{l k} \int_{0}^{h} W_{k}(t) \mathrm{d} W_{j}(t)$
where $a, b$ and its derivatives all evaluated at $(S(0), 0)$.

The problem now is to evaluate the iterated Itô integral

$$
I_{j k} \equiv \int_{0}^{h} W_{k}(t) \mathrm{d} W_{j}(t)
$$

## Lévy areas

Itô calculus gives us

$$
\mathrm{d}\left(W_{j} W_{k}\right)=W_{j} \mathrm{~d} W_{k}(t)+W_{k} \mathrm{~d} W_{j}(t)+\rho_{j k} \mathrm{~d} t
$$

where $\rho_{j k}$ is the correlation between $\mathrm{d} W_{j}$ and $\mathrm{d} W_{k}$. Hence,

$$
W_{j}(h) W_{k}(h)-\rho_{j k} h=I_{k j}+I_{j k}
$$

If we define the Lévy area to be

$$
A_{j k}=I_{k j}-I_{j k}=\int_{0}^{h} W_{j}(t) \mathrm{d} W_{k}(t)-W_{k}(t) \mathrm{d} W_{j}(t)
$$

then

$$
I_{j k}=\frac{1}{2}\left(W_{j}(h) W_{k}(h)-\rho_{j k} h-A_{j k}\right) \quad \text { MC Lecture 11- р. } 14
$$

## Lévy areas

The problem is that there is no easy way to simulate the Lévy areas:

- conditional distribution depends on $W_{j}(h)$ and $W_{k}(t)$ so can't simply invert a cumulative distribution function
- Lyons \& Gaines have an efficient technique in 2-dimensions but for higher dimensions, need to simulate Brownian motion within each timestep to approximate the Lévy area

However

- not all applications require it
- can be simulated very efficiently using many-core GPUs


## Milstein method

The Milstein method is

$$
\begin{aligned}
\widehat{S}_{i, n+1}= & \widehat{S}_{i, n}+a_{i, n} h+\sum_{j} b_{i j, n} \Delta W_{j, n} \\
& +\frac{1}{2} \sum_{j, k, l} \frac{\partial b_{i j}}{\partial S_{l}} b_{l k, n}\left(\Delta W_{j, n} \Delta W_{k, n}-\rho_{j k} h-A_{j k, n}\right)
\end{aligned}
$$

with

$$
A_{j k, n}=\int_{t_{n}}^{t_{n+1}}\left(W_{j}(t)-W_{j}\left(t_{n}\right)\right) \mathrm{d} W_{k}(t)-\left(W_{k}(t)-W_{k}\left(t_{n}\right)\right) \mathrm{d} W_{j}(t)
$$

## Milstein method

However, using $A_{j k}=-A_{k j}$,

$$
\begin{aligned}
\sum_{j, k, l} \frac{\partial b_{i j}}{\partial S_{l}} b_{l k} A_{j k, n} & =-\sum_{j, k, l} \frac{\partial b_{i j}}{\partial S_{l}} b_{l k} A_{k j, n} \\
& =-\sum_{j, k, l} \frac{\partial b_{i k}}{\partial S_{l}} b_{l j} A_{j k, n} \\
& =\frac{1}{2} \sum_{j, k, l}\left(\frac{\partial b_{i j}}{\partial S_{l}} b_{l k}-\frac{\partial b_{i k}}{\partial S_{l}} b_{l j}\right) A_{j k, n}
\end{aligned}
$$

and so the Lévy areas are not need if, for all $i, j, k$,

$$
\sum_{l} \frac{\partial b_{i j}}{\partial S_{l}} b_{l k}-\frac{\partial b_{i k}}{\partial S_{l}} b_{l j}=0
$$

## Milstein method

If $b$ is a non-singular diagonal matrix, so each component of $S(t)$ is driven by a separate component of $W(t)$, the commutativity condition reduces to

$$
\frac{\partial b_{i j}}{\partial S_{k}} b_{k k}-\frac{\partial b_{i k}}{\partial S_{j}} b_{j j}=0
$$

- if either $i=j=k$, or $i \neq j$ and $i \neq k$, this is satisfied
- if $i=j$ and $i \neq k$, it requires $\frac{\partial b_{i i}}{\partial S_{k}}=0$
- if $i=k$ and $i \neq j$, it requires $\frac{\partial b_{i i}}{\partial S_{j}}=0$
- hence, OK provided $b_{i i}$ depends only on $S_{i}$


## Final words

- Milstein scheme gives improved $O(h)$ strong convergence
- in vector case, needs simulation of Lévy areas in many cases, but not in some important applications
- weak convergence is not improved, so no benefit in most applications
- however, improved strong convergence does help with Multilevel Monte Carlo method
- other higher order methods have similar terms
- the Euler-Maruyama method has the highest order of accuracy achievable using just Brownian increments

