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Put some effort into the Cayley transf.

You have get straight ~~what~~ the C.T. is.

The simplest version maybe occurs in the case of the orthogonal group.

$$SO(n) = \{g \in GL(n, \mathbb{R}) \mid g^t g = I\}$$

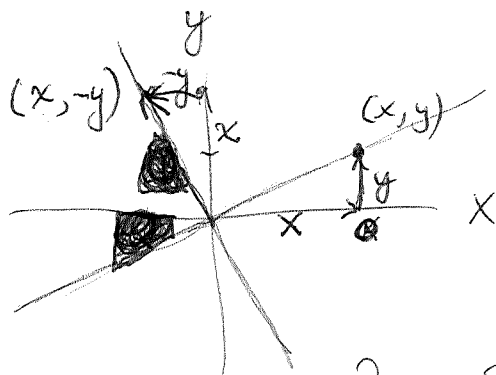
Lie  $SO(n) = \{X \in M_n(\mathbb{R}) \mid X^t + X = 0\}$ . In thiscase you have ~~some~~ a map from ~~the~~Lie  $SO(n)$  to  $SO(n)$  sending  $X$  to  $\frac{1+X}{1-X} = g$ 

$$g^{1/2} = \frac{1+X}{(1-X^2)^{1/2}}$$

$$g = \frac{(1+X)^2}{(1+X)(1-X)} = \frac{1+X}{1-X}$$

Notice that so far everything is taking place in  $M_n \mathbb{R}$  ~~in~~ in which you have the appropriate functional calculus, both  $\exp(tX)$ and  $\frac{1+tX}{1-tX}$ . Since a skew symmetric op  $X$ is a direct of infinitesimal 2d rotations:  $X = \omega \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$ ,It should be ~~possibly to~~ understand what's happening

$$\exp\left(\theta \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}\right) =$$



$$\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -y \\ x \end{bmatrix}$$

$$\exp\left(\theta \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}\right) = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \xrightarrow{\partial \theta} \begin{bmatrix} -\sin \theta & -\cos \theta \\ \cos \theta & -\sin \theta \end{bmatrix}$$

$$\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} = \begin{bmatrix} -\sin \theta & -\cos \theta \\ \cos \theta & -\sin \theta \end{bmatrix}$$

$$\int_0^{\infty} e^{-st} \dot{u} dt = \int_0^{\infty} \left\{ \frac{d}{dt} [e^{-st} u] + s e^{-st} u \right\} dt = -u(0) + s \hat{u}(s)$$

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~~and look at SO(2n)~~

Looking at

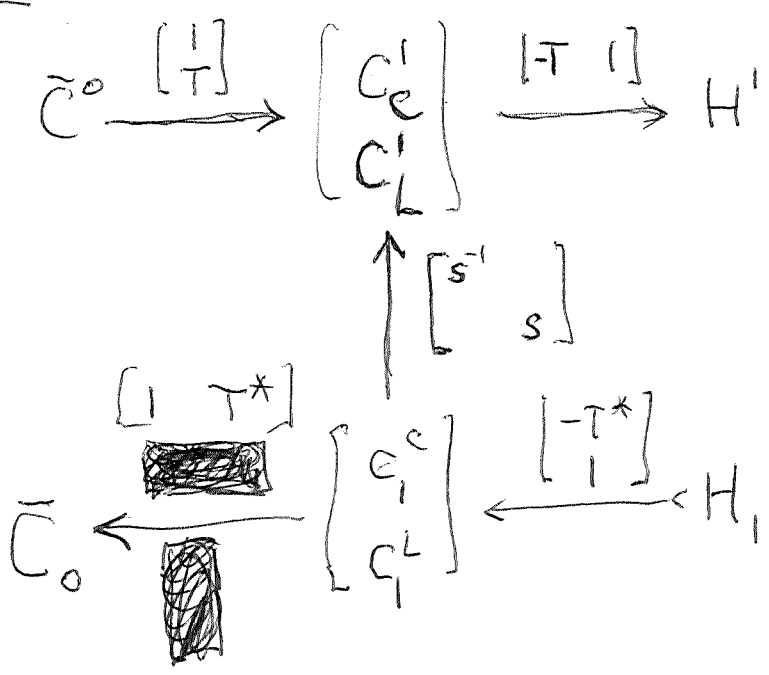
$O(n)$  or should it be  $SO(2n)$ ? The aim is to use the C.T. Lie  $O(n) \rightarrow SO(n)$ ,  $X \mapsto \frac{1+X}{1-X}$  to understand group elements.

~~and look at SO(2n)~~

You had an idea linking Cayley transform of  $X$  to frequencies for a harmonic oscillator. Involves inverse Cayley transform I think.

Given an orthogonal transformation  $g$  you want  $X$  skew-symmetric s.t.  $\frac{1+X}{1-X} = g$ . Then  $X$  is the infinitesimal generator of the time evolution for a harmonic oscillator. This is the "odd" ungraded case.

But there's also an even case, where  $X = \begin{bmatrix} 0 & -T^* \\ T & 0 \end{bmatrix}$



Important variables  
 $V_C$   $I_L$  dominant  
 $I_C$   $V_L$  weak

$$\dot{V}_C = I_C$$

$$\dot{I}_L = V_L$$

$$\hat{I}_C = \hat{V}_C = s \hat{V}_C - V_C(0)$$

$$\hat{V}_L = \hat{I}_L = s \hat{I}_L - I_L(0)$$

$$-T \hat{V}_C + \hat{V}_L = 0$$

$$\hat{I}_C + T^* \hat{I}_L = 0$$

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$$V_C(0) = s \hat{V}_C - \hat{I}_C = s \hat{V}_C + T^* \hat{I}_L$$

$$I_L(0) = s \hat{I}_L - \hat{V}_L = -T \hat{V}_C + s \hat{I}_L$$

$$\begin{bmatrix} s & +T^* \\ -T & s \end{bmatrix} \begin{bmatrix} \hat{V}_C \\ \hat{I}_L \end{bmatrix} = \begin{bmatrix} V_C(0) \\ I_L(0) \end{bmatrix}$$

$$s - \begin{bmatrix} 0 & -T^* \\ T & 0 \end{bmatrix}$$

~~Apply Laplace transform to the circuit equations~~

Harmonic oscillator

Ham eq

$$\dot{p} = -kq, \quad \dot{q} = m^{-1}p$$

$$X \begin{bmatrix} p \\ q \end{bmatrix} = \begin{bmatrix} \dot{p} \\ \dot{q} \end{bmatrix} = \begin{bmatrix} 0 & -k \\ m^{-1} & 0 \end{bmatrix} \begin{bmatrix} p \\ q \end{bmatrix}$$

$$H = \begin{bmatrix} m^{-1} & 0 \\ 0 & k \end{bmatrix} = \underbrace{\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}}_A \underbrace{\begin{bmatrix} 0 & -k \\ m^{-1} & 0 \end{bmatrix}}_X$$

$$X^t A + A X = 0 \quad \text{because } \cancel{A^t X} \quad \cancel{A X}$$

$$A X = H \quad (A X)^t = H^t \Leftrightarrow -X^t A = H \quad \therefore A X = -X^t A$$

$$\underbrace{X^t A X}_H + \underbrace{A X X}_H = 0. \quad \text{Can you get anywhere?}$$

~~What is the point? The frequency of the oscillator is  $\omega = \sqrt{k/m}$ . The period is  $T = 2\pi/\omega = 2\pi\sqrt{m/k}$ .~~

$$X^2 = \begin{bmatrix} 0 & -k \\ m^{-1} & 0 \end{bmatrix} \begin{bmatrix} 0 & -k \\ m^{-1} & 0 \end{bmatrix} = \begin{bmatrix} -km^{-1} & 0 \\ 0 & +m^{-1}k \end{bmatrix} = - \begin{bmatrix} km^{-1} & 0 \\ 0 & m^{-1}k \end{bmatrix}$$

$$-X^2 = \begin{bmatrix} km^{-1} & 0 \\ 0 & m^{-1}k \end{bmatrix}$$

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Go to binder about ham osc., C.T. and look for results.

$$H = \begin{bmatrix} m^{-1} & 0 \\ 0 & k \end{bmatrix} : \begin{bmatrix} V_+ \\ V_- \end{bmatrix} \rightarrow \begin{bmatrix} V_+^n \\ V_-^n \end{bmatrix}$$

do the "mechanical" harmonic oscillator  $H = \frac{1}{2} \dot{p} m^{-1} p + \frac{1}{2} k q^2$

$$\dot{p} = -\frac{\partial H}{\partial q} = -kq, \quad \dot{q} = \frac{\partial H}{\partial p} = m^{-1}p$$

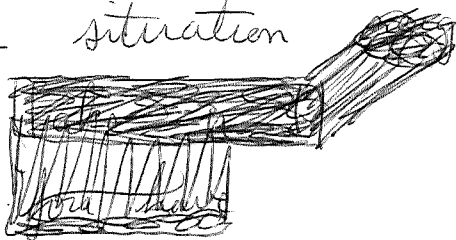
$$\begin{bmatrix} \dot{p} \\ \dot{q} \end{bmatrix} = \underbrace{\begin{bmatrix} 0 & -k \\ m^{-1} & 0 \end{bmatrix}}_X \begin{bmatrix} p \\ q \end{bmatrix}$$

$$A X = H$$

$$\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} 0 & -k \\ m^{-1} & 0 \end{bmatrix} = \begin{bmatrix} km^{-1} & 0 \\ 0 & k \end{bmatrix}$$

what's going on here? You have a  $2n$  dimensional phase space of  $\begin{bmatrix} p \\ q \end{bmatrix}$  with symplectic form  $\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} = A$  and pos symm form  $\begin{bmatrix} m^{-1} & 0 \\ 0 & k \end{bmatrix} = H$ .

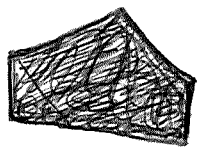
Question. How do you get from this picture to the situation of  $Sp(2n)$ ?



Take  $n=1$ .

$$-X^2 = \begin{bmatrix} 0 & -k \\ m^{-1} & 0 \end{bmatrix} \begin{bmatrix} 0 & k \\ -m^{-1} & 0 \end{bmatrix} = \begin{bmatrix} km^{-1} & 0 \\ 0 & m^{-1}k \end{bmatrix}$$

$$X = A^{-1}H = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} m^{-1} & 0 \\ 0 & k \end{bmatrix} = \begin{bmatrix} 0 & -k \\ m^{-1} & 0 \end{bmatrix}$$



Another idea you've forgotten



$$L = \frac{1}{2} \dot{q}^t m \dot{q} - \frac{1}{2} q^t k q, \quad p = \frac{\partial L}{\partial \dot{q}} = m \dot{q}, \quad \frac{\partial L}{\partial q} = -kq$$

$$m \ddot{q} + kq = 0$$

frequencies  $m\omega^2 + k = 0$   
 $m^{-1}k$  has real  $> 0$  eigenvalues  
 WHY?

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~~xxxxxx~~  $x^t k x \geq 0$  for  $x \neq 0$

$x^t (m(m^{-1}k)) x > 0$ . Other way to proceed

is via  $m^{1/2}$ ?  $m$  pos symmetric has a positive symm.  $m^{1/2}$ . The point is that  $m^{-1}k$  is symmetric wrt the <sup>pos.</sup> inner prod  $x^t m x$

~~$(m^{-1}kx)^t m (m^{-1}k)x = x^t k m^{-1} m m^{-1} k x$~~   
 ~~$(m^{-1}kx)^t m x = x^t m^{-1} k x$~~

$(m^{-1}kx)^t m x \stackrel{?}{=} x^t m (m^{-1}kx)$   
 $x^t (m^{-1}k)^t m x = x^t k m^{-1} m x = x^t k x$

The problem: Apparently there is a simple way to get the frequencies, namely the eigenvalues of the operator  $m^{-1}k$  or  $km^{-1}$ . ~~But that~~  
~~is not~~ None of this looks symplectic

$X = \begin{bmatrix} 0 & -k \\ m^{-1} & 0 \end{bmatrix} = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} m^{-1} & 0 \\ 0 & k \end{bmatrix}$

$-X^2 = -\begin{bmatrix} 0 & -k \\ m^{-1} & 0 \end{bmatrix} \begin{bmatrix} 0 & -k \\ m^{-1} & 0 \end{bmatrix} = \begin{bmatrix} +km^{-1} & 0 \\ 0 & +m^{-1}k \end{bmatrix} = \begin{bmatrix} km^{-1} & 0 \\ 0 & m^{-1}k \end{bmatrix}$

$\frac{1+X}{(1-X^2)^{1/2}}$   
 $1+X = \begin{bmatrix} 1 & -k \\ +m^{-1} & 1 \end{bmatrix} \begin{bmatrix} (1+km^{-1})^{-1/2} & 0 \\ 0 & (1+m^{-1}k)^{-1/2} \end{bmatrix}$   
 $= \begin{bmatrix} \frac{1}{(1+km^{-1})^{1/2}} & -k \frac{1}{(1+m^{-1}k)^{1/2}} \\ m^{-1} \frac{1}{(1+km^{-1})^{1/2}} & \frac{1}{(1+m^{-1}k)^{1/2}} \end{bmatrix}$

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$$X \begin{bmatrix} p \\ g \end{bmatrix} = \begin{bmatrix} \dot{p} \\ \dot{g} \end{bmatrix} = \begin{bmatrix} -k g \\ m^{-1} p \end{bmatrix} = \begin{bmatrix} 0 & m^{-1} g \\ -k & 0 \end{bmatrix} \begin{bmatrix} p \\ g \end{bmatrix}$$

$$X = \begin{bmatrix} 0 & -k \\ m^{-1} & 0 \end{bmatrix} = A^{-1}H = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} m^{-1} & 0 \\ 0 & k \end{bmatrix} \Rightarrow \begin{bmatrix} 0 & -k \\ m^{-1} & 0 \end{bmatrix} \begin{bmatrix} p \\ g \end{bmatrix}$$

Can you combine A, H to get the eigenvalues?

$$\begin{bmatrix} 0 & -k \\ m^{-1} & 0 \end{bmatrix}$$

$$\begin{bmatrix} m^{-1} & \lambda \\ -\lambda & k \end{bmatrix} = \lambda A + H = A[\lambda + A^{-1}H] = A[\lambda + X]$$

Yes

~~...~~ ~~...~~  $X = A^{-1}H$

$$\therefore \lambda - X = \lambda - A^{-1}H = A^{-1}(\lambda A - H)$$

Go back to the ~~LC~~ LC network idea that the network gives rise to a rep of  $\langle F, \varepsilon \rangle$  and the dynamics of the network are obtained via L.T. from  $(s - X)^{-1}$ , where X is the I.C.T. of  $F\varepsilon = g$ .

~~pp. w''~~ Introduce orth. coords. At the moment

you have  $A = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$   $\begin{bmatrix} p_1 \\ g_1 \end{bmatrix}^t \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} p_2 \\ g_2 \end{bmatrix} = p_1^t g_2 - g_1^t p_2$

$$H = \begin{bmatrix} m^{-1} & 0 \\ 0 & k \end{bmatrix} \quad X = A^{-1}H = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} m^{-1} & 0 \\ 0 & k \end{bmatrix} = \begin{bmatrix} 0 & -k \\ m^{-1} & 0 \end{bmatrix} \quad \text{"(kg)^t (kg)}$$

Use Gram-Schmidt  $k = K^t K$   $g^t k g = \overbrace{g^t K^t K g}^{\text{"(kg)^t (kg)"}}$

~~...~~ K is a symmetric pos. def matrix

pp. w'' thru v''' need clarification about the mechanical harmonic oscillator.

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$$SU(2) = \left\{ \begin{bmatrix} a & b \\ -\bar{b} & \bar{a} \end{bmatrix} : |a|^2 + |b|^2 = 1 \right\}$$

$$\mathcal{L} SU(2) = \left\{ X = \begin{bmatrix} a & b \\ -\bar{b} & \bar{a} \end{bmatrix} : \begin{array}{l} a + \bar{a} = 0 \\ a = i\alpha \end{array} \right\}, \alpha \text{ real}$$

$$\mathcal{L} SU(2) = \left\{ X = \begin{bmatrix} i\alpha & b \\ -\bar{b} & -i\alpha \end{bmatrix} : \alpha \text{ real} \right\}$$

$$X^2 = \begin{bmatrix} i\alpha & b \\ -\bar{b} & -i\alpha \end{bmatrix} \begin{bmatrix} i\alpha & b \\ -\bar{b} & -i\alpha \end{bmatrix} = \begin{bmatrix} -\alpha^2 - |b|^2 & 0 \\ 0 & -\alpha^2 - |b|^2 \end{bmatrix} = -1$$

~~...~~  $J = \begin{bmatrix} i\alpha & b \\ -\bar{b} & -i\alpha \end{bmatrix} \in \mathcal{L} SU(2)$

and  $J \in SU(2)$  when  $\alpha^2 + |b|^2 = 1$ .

$$\mathfrak{f} = \{-J = J^* = J^{-1}\} = \mathfrak{J}^2$$

So  $J^2 = -1 \implies$  ~~...~~  $e^{\theta J} = \sum_{n=0}^{\infty} \frac{\theta^{2n} J^{2n}}{(2n)!} + \sum_{n=0}^{\infty} \frac{\theta^{2n+1} J^{2n+1}}{(2n+1)!}$

$e^{\theta J} = \cos \theta + (\sin \theta) J$  so  $e^{\pi J} = -1, e^{\frac{\pi}{2} J} = J$

basepoint  $\varepsilon = \begin{bmatrix} i & 0 \\ 0 & -i \end{bmatrix}$

$$\left. \begin{array}{l} \varepsilon J + \underbrace{(-J)\varepsilon}_{(\varepsilon J)^*} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} i\alpha & b \\ -\bar{b} & -i\alpha \end{bmatrix} = \begin{bmatrix} i\alpha & b \\ \bar{b} & i\alpha \end{bmatrix} \\ + \begin{bmatrix} i\alpha & b \\ -\bar{b} & -i\alpha \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} i\alpha & -b \\ -\bar{b} & i\alpha \end{bmatrix} \end{array} \right\} = 2 \begin{bmatrix} i\alpha & 0 \\ 0 & i\alpha \end{bmatrix}$$

$$\frac{i\varepsilon J - J i\varepsilon}{2} = \alpha \quad (i\varepsilon)J + (-J)(-i\varepsilon) = i(\varepsilon J + J\varepsilon)$$

Try again  $\varepsilon J + (\varepsilon J)^* = \varepsilon J + (-J)\varepsilon = 2 \begin{bmatrix} i\alpha & 0 \\ 0 & i\alpha \end{bmatrix}$

$I, J \in \mathfrak{f}$   $IJ + JI$  should be hermitian.  
 $(IJ)^* = (-J)(-I) = JI$

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Try exponentiating  $\begin{bmatrix} 0 & i\beta \\ -i\beta & 0 \end{bmatrix}$ . This may be wrong. But perhaps you can diagonalize.  $b, \bar{b}$

Recall  $J^2 = \begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix}^2 = \begin{bmatrix} -b\bar{b} & 0 \\ 0 & -\bar{b}b \end{bmatrix} = -I$

so  $b\bar{b} = \bar{b}b = I$ . Also  $b = b^t$  is assumed so that  $\bar{b} = b^*$ . Thus  $b^t = b^*$  (so  $b \in U(n)$ ) and  $b = b^t$  so that  $b$  is symmetric. The idea now is to diagonalize  $b$  using the action of  $U(n)$  given by  $u \cdot b = ubu^t = ub\bar{u}^{-1}$ .

Perhaps you should try to follow the conjugacy theorem in the Lie algebra. This proceeds by minimizing the distance squared between a ~~the~~  $U(n)$  orbit of  $b$  and a generic diagonal element.

List of steps. The basic action is  $u \cdot b = ubu^t = ub\bar{u}^{-1}$  ~~of~~ of  $U(n)$  on complex symmetric matrices of size  $n \times n$ . Suppose  $b = \text{diag}(\lambda_1, \dots, \lambda_n)$ .

What is the isotropy group?  $n=1$ . Then  $u \cdot b = ubu^t = u^2b$ , here  $u = e^{i\theta}$ . If  $b \neq 0$  the isotropy group is  $\{u = \pm 1\}$ . Next take  $n=2$ , where  $b_1 \neq b_2$  are distinct  $\neq 0$  complex numbers.

say ~~the~~  $u = \begin{bmatrix} \alpha & \beta \\ \gamma & \delta \end{bmatrix}$

$$\begin{bmatrix} \alpha & \beta \\ \gamma & \delta \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \begin{bmatrix} \alpha & \gamma \\ \beta & \delta \end{bmatrix}$$

It seems that you ought to be able to use  $SU(2)$ .



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$$\begin{bmatrix} a & b \\ -\bar{b} & \bar{a} \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \begin{bmatrix} a & -\bar{b} \\ b & \bar{a} \end{bmatrix} = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$$

$$\begin{bmatrix} a & b \\ -b & \bar{a} \end{bmatrix} \begin{bmatrix} \lambda_1 \\ \lambda_2 \end{bmatrix} = \begin{bmatrix} \lambda_1 & \\ & \lambda_2 \end{bmatrix} \begin{bmatrix} \bar{a} & \bar{b} \\ -b & a \end{bmatrix}$$

$$\begin{bmatrix} \lambda_1 a & \lambda_2 b \\ -\lambda_1 b & \lambda_2 \bar{a} \end{bmatrix} = \begin{bmatrix} \lambda_1 \bar{a} & \lambda_1 \bar{b} \\ -\lambda_2 b & \lambda_2 a \end{bmatrix}$$

$$\begin{bmatrix} \alpha & \beta \\ \gamma & \delta \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \begin{bmatrix} \alpha & \gamma \\ \beta & \delta \end{bmatrix}$$

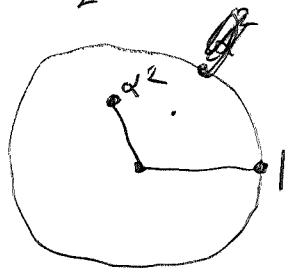
$$\begin{bmatrix} \lambda_1 \alpha & \lambda_2 \beta \\ \lambda_1 \gamma & \lambda_2 \delta \end{bmatrix} \begin{bmatrix} \alpha & \gamma \\ \beta & \delta \end{bmatrix} = \begin{bmatrix} \lambda_1 \alpha^2 + \lambda_2 \beta^2 & \lambda_1 \alpha \gamma + \lambda_2 \beta \delta \\ \lambda_1 \gamma \alpha + \lambda_2 \delta \beta & \lambda_1 \gamma^2 + \lambda_2 \delta^2 \end{bmatrix}$$

$$\lambda_1 \gamma \alpha + \lambda_2 \delta \beta = 0 \quad |\lambda_1| |\gamma| |\alpha| = |\lambda_2| |\delta| |\beta|$$

but you know  $|\alpha|^2 + |\beta|^2 = 1$   $\therefore |\beta| = |\gamma|$   
 $|\alpha|^2 + |\gamma|^2 = 1$

Finally  $\lambda_1 = \lambda_1 \alpha^2 + \lambda_2 \beta^2$   $\lambda_1 (1 - \alpha^2) = \lambda_2 \beta^2$   
 $\lambda_2 = \lambda_1 \gamma^2 + \lambda_2 \delta^2$   $\lambda_2 (1 - \delta^2) = \lambda_1 \gamma^2$

suppose  $\lambda_1 > \lambda_2 > 0$



$$\lambda_1 |1 - \alpha^2| = \lambda_2 |\beta|^2 = \lambda_2 (1 - |\alpha|^2)$$

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Diagonalization ~~for self-adjoint matrices~~

for self-adjoint matrices  $A$ . Pick a diagonal matrix  $D$  with distinct real eigenvalues. Define a functional  $\frac{1}{2} \text{tr} (D - uAu^{-1})^2 = \Phi(u)$ . Because  $U(n)$  is compact  $\exists$  a critical point  $u_0$ . Then consider a tangent vector  $u_0 X$  at ~~the~~  $u_0$

~~the~~  $\Phi(u_0 + \epsilon u_0 X) - \Phi(u_0)$

$$= \frac{1}{2} \text{tr} (D - u_0(1 + \epsilon X)A(1 - \epsilon X)u_0)$$

$$\Phi(u_0 + \delta u) - \Phi(u_0) =$$

$$\delta \frac{1}{2} \text{tr} (uAu^{-1} - D)^2 = \text{tr} [(uAu^{-1} - D) \cdot \delta(uAu^{-1})]$$

$$\delta(uAu^{-1}) = uXu^{-1} - uAu^{-1}Xu^{-1} = u[X, A]u^{-1}$$

$$\text{tr} ((uAu^{-1} - D) \cdot u[X, A]u^{-1})$$

$$= \text{tr} ((A - u^{-1}Du) \cdot [X, A]) = \text{tr} ([A, A - u^{-1}Du] X)$$

$A, D$  hermitian,  $D$  diagonal with distinct eigenvalues

minimize  $\frac{1}{2} \text{tr} (uAu^{-1} - D)^2$ . to prove  $\exists u$  such that

$$[uAu^{-1}, D] = 0. \quad \exists u_0 \text{ critical point of } \frac{1}{2} \text{tr} (u_0Au_0^{-1} - D)^2$$

Replace  $A$  by  $u_0^{-1}Au_0$  ?? Logic?

Let  $u = u_0$  be a critical point of  $\frac{1}{2} \text{tr} (uAu^{-1} - D)^2$

$$= \frac{1}{2} \text{tr} (A - u^{-1}Du)^2. \quad A, D \text{ hermitian. Claim}$$

$\frac{1}{2} \text{tr} (uAu^{-1} - D)^2$  has a critical point at  $u = I$

$$\Leftrightarrow [A, D] = 0. \quad \frac{1}{2} \text{tr} ((1+X)A(1-X) - D)^2$$

$A + [X, A]$

$$\textcircled{103} \quad \delta \frac{1}{2} \text{tr}(uAu^{-1} - D)^2 = \text{tr}(uAu^{-1} - D)([X, A])$$

$$= 0 \quad \forall X. \quad \frac{1}{2} \text{tr}((1+X)A(1-X) \cdot (A-D)) = 0$$

$$A + [X, A]$$

$$\delta \frac{1}{2} \text{tr}(uAu^{-1} - D)^2 = \text{tr}(\delta(uAu^{-1}) \cdot (uAu^{-1} - D))$$

$$u + \delta u = 1 + X$$

$$\text{tr}([X, A] \cdot (A-D))$$

$$\text{tr}(X \cdot [A, A-D])$$

$$\text{tr}([X, Y]Z) = \text{tr}(X[Y, Z]) = \text{tr}([Z, X], Y)$$

$$XYZ - YXZ$$

$$XYZ - XZY$$

$$\mathbb{L} \, \mathfrak{sp}(2n) = \left\{ X = \begin{bmatrix} a & b \\ -\bar{b} & \bar{a} \end{bmatrix} : \begin{array}{l} a^* = -a \\ b^* = b \end{array} \right\}$$

Cartan subalg is where  $a = \begin{bmatrix} s_1 & & \\ & \ddots & \\ & & s_n \end{bmatrix}$   $\bar{s}_i = -s_i$

Action  $a \# b = ab - b\bar{a} = ab + ba^t$

Let  $\hat{a}_{ij}$  denote the matrix with  $\begin{cases} 1 & \text{in } i, j \\ 0 & \text{otherwise} \end{cases}$

$$s \# \hat{a}_{ij} = (s_i - s_j) \hat{a}_{ij}. \quad \text{Let } \hat{b}_{ij} = \begin{cases} 1 & \text{position } i, j \\ 0 & \text{otherwise} \end{cases}$$

$$s \# \hat{b}_{ij} = s \hat{b}_{ij} - \hat{b}_{ij} \bar{s} = s_i \hat{b}_{ij} - \hat{b}_{ij} \bar{s}_j = (s_i + s_j) \hat{b}_{ij}$$

You're confused real + complex for the  $b$  root space.  
 When you write  $a \# b = ab - b\bar{a}$ ? You have to  
 straighten out the

184 Go back to  $\mathcal{L} Sp(2n) = \left\{ X = \begin{bmatrix} a & b \\ -\bar{b} & \bar{a} \end{bmatrix} : \begin{matrix} a^* = -a \\ b^t = b \end{matrix} \right\}$

Have embedding  $U(n) \hookrightarrow Sp(2n)$ ,  $u \mapsto \begin{bmatrix} u & 0 \\ 0 & \bar{u} \end{bmatrix} = \begin{bmatrix} u & 0 \\ 0 & (u^t)^{-1} \end{bmatrix}$

$U \# B = \begin{bmatrix} u & 0 \\ 0 & \bar{u} \end{bmatrix} \begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix} \begin{bmatrix} u^* & 0 \\ 0 & u^t \end{bmatrix} = \begin{bmatrix} ubu^* & 0 \\ -\bar{u}b\bar{u}^* & 0 \end{bmatrix}$ . *Your*

aim is a conjugacy theorem that  $\forall B \exists U$  such that  $U \# B = UBU^*$  centralizes some  $B_0$ .

You are working in the space ~~of matrices~~

$B = \left\{ \begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix} \mid b^t = b \right\}$ . Functional  $\frac{1}{2} \text{tr}(UBU^* - B_0)^2$

Let  $U$  be a critical point, ~~let  $U$  be a critical point~~

Functional stationary for <sup>1st order</sup> variation  $U + \delta U = (1 + \epsilon X)U$

$\delta \frac{1}{2} \text{tr}(UBU^* - B_0)^2 = \text{tr} \{ \delta(UBU^* - B_0) (UBU^* - B_0) \}$

~~$= -\frac{1}{2} \text{tr}(UBU^* - B_0)^2 + \frac{1}{2} \text{tr}((U + \delta U)B(U + \delta U)^* - B_0)^2$~~

$= \delta \left\{ \frac{1}{2} \text{tr} \left( \underbrace{UBU^*}_{UBU^*} - UBU^*B_0 - B_0UBU^* + B_0^2 \right) \right\}$

$= -\frac{1}{2} \text{tr} \delta \{ 2UBU^*B_0 \} = -\text{tr} \{ \delta(UBU^*B_0) \}$

$= -\text{tr} \{ (1 + \epsilon X)B(1 - \epsilon X)B_0 \}$

~~...  $\epsilon[X, B]$  ...~~

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Look at  $\mathcal{L}O(2n) = \left\{ X = \begin{bmatrix} a & b \\ b & \bar{a} \end{bmatrix} : \begin{matrix} a^* = -a \\ b^t = -b \end{matrix} \right\}$

$K = \left\{ \begin{bmatrix} u & 0 \\ 0 & \bar{u} \end{bmatrix} : u \in U(n) \right\}$   $p = \begin{bmatrix} 0 & b \\ b & 0 \end{bmatrix} : b^t = -b$

$$\underbrace{\begin{bmatrix} u & 0 \\ 0 & \bar{u} \end{bmatrix}}_K \underbrace{\begin{bmatrix} 0 & b \\ b & 0 \end{bmatrix}}_p \underbrace{\begin{bmatrix} u^* & 0 \\ 0 & u^t \end{bmatrix}}_{K^{-1}} = \begin{bmatrix} 0 & ubu^* \\ \bar{u}b\bar{u}^t & 0 \end{bmatrix}$$

$$\Phi(K) = \frac{1}{2} \text{tr} (KpK^{-1} - p_0)^2 \quad K = \begin{bmatrix} u & 0 \\ 0 & \bar{u} \end{bmatrix}$$

~~Let  $u_0$  be a stationary point:  $\Phi(u_0 + \delta u) = \Phi(u_0)$   
can take  $\delta u = \epsilon X u_0$  Let  $K_0 = \begin{bmatrix} u_0 & 0 \\ 0 & \bar{u}_0 \end{bmatrix}$  be~~

a stationary point,  $K + \delta K = K_0 + \epsilon X K_0$   $X = \begin{bmatrix} a & 0 \\ 0 & \bar{a} \end{bmatrix}$

$$\left( (1 + \epsilon X) K_0 p K_0^{-1} (1 - \epsilon X) - p_0 \right)^2$$

$$\frac{1}{2} \text{tr} (KpK^{-1} - p_0)^2 = \frac{1}{2} \text{tr} \left[ (KpK^{-1})^2 - KpK^{-1}p_0 - p_0 KpK^{-1} + p_0^2 \right]$$

$$= \text{tr} (p^2 + p_0^2) - \text{tr} (KpK^{-1}p_0)$$

Assuming  ~~$K_0$~~   $K_0$  stationary point for  $\text{tr} (K_0 p K_0^{-1} p_0)$  take  $K_0 + \delta K = (1 + \epsilon X) K_0$   $X = \begin{bmatrix} a & 0 \\ 0 & \bar{a} \end{bmatrix}$

$$\text{tr} \left( (1 + \epsilon X) K_0 p K_0^{-1} (1 - \epsilon X) p_0 \right)$$

$$= \text{tr} (K_0 p K_0^{-1} p_0) + \epsilon \text{tr} \left( [X, K_0 p K_0^{-1}] p_0 \right)$$

$$\pm \epsilon \text{tr} (X [K_0 p K_0^{-1}, p_0])$$

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~~Centralizer of~~

Centralizer of a generic  $p_0$

$$p_0 = \begin{bmatrix} 0 & b_0 \\ \bar{b}_0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} u & 0 \\ 0 & \bar{u} \end{bmatrix} \begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix} \begin{bmatrix} u^* & 0 \\ 0 & u^t \end{bmatrix} = \begin{bmatrix} 0 & ubu^t \\ \bar{u}\bar{b}u^* & 0 \end{bmatrix}$$

inf action  $\left[ \begin{bmatrix} a & 0 \\ 0 & \bar{a} \end{bmatrix}, \begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix} \right] = \begin{bmatrix} 0 & ab+ba^t \\ \bar{a}\bar{b}+\bar{b}\bar{a}^* & 0 \end{bmatrix}$

$b=1$ .  $\begin{bmatrix} u & 0 \\ 0 & \bar{u} \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} u^* & 0 \\ 0 & u^t \end{bmatrix} = \begin{bmatrix} uut & 0 \\ 0 & \bar{u}u^* \end{bmatrix} \stackrel{?}{=} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$

iff  $uut = 1$        $\bar{u} = u$   
 $\bar{u}u^* = 1 \Rightarrow \bar{u}u^* = u$

$$\begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix} = \begin{bmatrix} & \lambda_1 \dots \lambda_n \\ \bar{\lambda}_1 \dots \bar{\lambda}_n & \end{bmatrix}$$

$$\begin{bmatrix} a & 0 \\ 0 & \bar{a} \end{bmatrix}, \begin{bmatrix} 0 & \Lambda \\ \bar{\Lambda} & 0 \end{bmatrix} = \begin{bmatrix} 0 & a\Lambda \\ \bar{a}\bar{\Lambda} & 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & \Lambda \\ \bar{\Lambda} & 0 \end{bmatrix} \cdot \begin{bmatrix} a & 0 \\ 0 & \bar{a} \end{bmatrix} = \begin{bmatrix} 0 & \Lambda\bar{a} \\ \bar{\Lambda}a & 0 \end{bmatrix}$$

$$\begin{bmatrix} a\Lambda - \Lambda\bar{a} \\ \bar{a}\bar{\Lambda} - \bar{\Lambda}a \end{bmatrix}$$

$\Lambda=1$ , then  $\begin{bmatrix} a & 0 \\ 0 & \bar{a} \end{bmatrix}$  centralizes

$\Lambda \Leftrightarrow a = \bar{a}$ . Next compute

$$\begin{bmatrix} a_{ij} \end{bmatrix} \begin{bmatrix} \lambda_1 \\ \vdots \\ \lambda_n \end{bmatrix} - \begin{bmatrix} \lambda_1 \\ \vdots \\ \lambda_n \end{bmatrix} \begin{bmatrix} \bar{a}_{ij} \end{bmatrix} = 0$$

$$\begin{bmatrix} a_{ij} \end{bmatrix} \begin{bmatrix} \lambda_1 \\ \vdots \\ \lambda_n \end{bmatrix} + \begin{bmatrix} \lambda_1 \\ \vdots \\ \lambda_n \end{bmatrix} \begin{bmatrix} a_{ji} \end{bmatrix} = 0$$

?

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take  $b = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$

$$P = \left[ \begin{array}{c|c} 0 & \lambda_1 \\ \hline \lambda_1 & 0 \end{array} \right]$$

$$X = \left[ \begin{array}{cc|cc} a & b & & \\ c & d & & \\ \hline & & \bar{a} & \bar{b} \\ & & \bar{c} & \bar{d} \end{array} \right] \quad \begin{array}{l} \bar{a} = -a \\ \bar{d} = -d \\ \bar{b} = -c \end{array}$$

$$XP = \left[ \begin{array}{cc|cc|cc} a & b & 0 & 0 & \lambda_1 & \lambda_2 \\ c & d & 0 & 0 & & \\ \hline 0 & \bar{a} & \bar{b} & \lambda_1 & & 0 \\ & \bar{c} & \bar{d} & \lambda_2 & & \end{array} \right] = \left[ \begin{array}{cc|cc} a\lambda_1 & b\lambda_2 & & \\ c\lambda_1 & d\lambda_2 & & \\ \hline \bar{a}\lambda_1 & \bar{b}\lambda_2 & & 0 \\ \bar{c}\lambda_1 & \bar{d}\lambda_2 & & \end{array} \right]$$

~~$$PX = \left[ \begin{array}{cc|cc|cc} a & b & \lambda_1 \bar{a} & \lambda_1 \bar{b} & & \\ c & d & \lambda_2 \bar{c} & \lambda_2 \bar{d} & & \\ \hline \lambda_1 \bar{a} & \lambda_1 \bar{b} & & & & \\ \lambda_2 \bar{c} & \lambda_2 \bar{d} & & & & \end{array} \right]$$~~

$$PX = \left[ \begin{array}{c|c} \lambda_1 & a \ b \\ \lambda_2 & c \ d \\ \hline \lambda_1 & \bar{a} \ \bar{b} \\ \lambda_2 & \bar{c} \ \bar{d} \end{array} \right] = \left[ \begin{array}{c|c} 0 & \lambda_1 \bar{a} \ \lambda_1 \bar{b} \\ \lambda_1 \bar{a} \ \lambda_1 \bar{b} & 0 \\ \hline \lambda_2 \bar{c} \ \lambda_2 \bar{d} & \\ \lambda_2 \bar{c} \ \lambda_2 \bar{d} & 0 \end{array} \right]$$

$$\begin{array}{l} a\lambda_1 = \lambda_1 \bar{a} \\ c\lambda_1 = \lambda_2 \bar{c} \end{array} \quad \begin{array}{l} b\lambda_2 = \lambda_1 \bar{b} \\ d\lambda_2 = \lambda_2 \bar{d} \end{array}$$

∴  $\lambda_1 \neq 0$ , then  $a = \bar{a} \Rightarrow a = 0$

∴  $\lambda_2 \neq 0$ , then  $d = \bar{d} \Rightarrow d = 0$

∴  $|\lambda_1| \neq |\lambda_2|$  then  $|d| = 0$

$$a\lambda_1 = \lambda_1(-a)$$

$$b\lambda_2 = \lambda_1(-c)$$

Ass  $\lambda_1, \lambda_2 \neq 0$   
then  $a = d = 0$ .

$$c\lambda_1 = \lambda_2(-b)$$

$$d\lambda_2 = \lambda_2(-d)$$

Suppose  $\begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ . Then you

seem to get  $a = \bar{a}$ ,  $b = \bar{b}$ ,  $c = \bar{c}$ ,  $d = \bar{d}$ .  $\therefore \begin{bmatrix} a & b \\ c & d \end{bmatrix}$   
 is real and ~~skew symmetric~~ skew adjoint, therefore  
 real skew symmetric  $a = d = 0$   $b = -c$ .  $\begin{bmatrix} 0 & b \\ -b & 0 \end{bmatrix}$ .

Assume  $\lambda_1, \lambda_2 \neq 0$ . Then  $a = d = 0$ .

$$XP - PX = \begin{bmatrix} & \\ & \end{bmatrix}$$

$$\begin{bmatrix} a\lambda_1 - \lambda_1 \bar{a} & b\lambda_2 - \lambda_1 \bar{b} \\ c\lambda_1 - \lambda_2 \bar{c} & d\lambda_2 - \lambda_2 \bar{d} \end{bmatrix} = \begin{bmatrix} \lambda_1 \overbrace{(a - \bar{a})}^{2a} & \\ & \lambda_2 \underbrace{(d - \bar{d})}_{2d} \end{bmatrix}$$

$$c = -\bar{b}$$

$$b\lambda_2 + \lambda_1 c$$

You see that  $c\lambda_1 - \lambda_2 \bar{c} = c\lambda_1 + \lambda_2 b$   
 $b\lambda_2 - \lambda_1 \bar{b} = b\lambda_2 + \lambda_1 c$  "

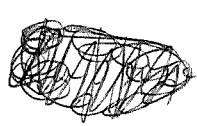
?

Take  $P_0 = \begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix}$   $b^t = -b$

$$\text{Lie } O(2n) = \left\{ X = \begin{bmatrix} a & b \\ \bar{b} & \bar{a} \end{bmatrix} : \begin{array}{l} a^* = -a \\ b^t = -b \end{array} \right\}$$



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$$K = \begin{bmatrix} a & 0 \\ 0 & \bar{a} \end{bmatrix}, P = \begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix}$$

b diag

$$a = [a_{ij}] \quad a_{ij} = \bar{a}_{ji} \quad b = \begin{bmatrix} \lambda_1 & \\ & \lambda_n \end{bmatrix} \quad b_{ij} = \lambda_i \delta_{ij} \quad \text{no sum ans.}$$

$$(ab)_{ik} = \sum_j a_{ij} \lambda_j \delta_{jk} = a_{ik} \lambda_k, \quad (b\bar{a})_{ik} = \sum_j \lambda_i \delta_{ij} \bar{a}_{jk} = \lambda_i \bar{a}_{ik}$$

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} = \begin{bmatrix} a_{11}\lambda_1 & a_{12}\lambda_2 \\ a_{21}\lambda_1 & a_{22}\lambda_2 \end{bmatrix}$$

action

$$a \# b = ab + ba^t = ab - b\bar{a}$$

$$\begin{bmatrix} \lambda_1 & \\ & \lambda_2 \end{bmatrix} \begin{bmatrix} \bar{a}_{11} & \bar{a}_{12} \\ \bar{a}_{21} & \bar{a}_{22} \end{bmatrix} = \begin{bmatrix} \lambda_1 \bar{a}_{11} & \lambda_1 \bar{a}_{12} \\ \lambda_2 \bar{a}_{21} & \lambda_2 \bar{a}_{22} \end{bmatrix}$$

$$= \begin{bmatrix} \lambda_1 a_{11} & \lambda_1 a_{21} \\ \lambda_2 a_{12} & \lambda_2 a_{22} \end{bmatrix}$$

~~$a_{11}\lambda_1 = -a_{11}\lambda_1$~~

$$\begin{aligned} a_{11}\lambda_1 &= -a_{11}\lambda_1 & a_{22}\lambda_2 &= -\lambda_2 a_{22} & \therefore a_{11} &= a_{22} = 0 \\ a_{12}\lambda_2 &= -a_{21}\lambda_1 & a_{21}\lambda_1 &= -a_{12}\lambda_2 & \text{single} \end{aligned}$$

plus single relation  $\frac{a_{12}\lambda_2}{+\lambda_1} + \frac{a_{21}\lambda_1}{-\lambda_2} = 0 \quad \therefore a_{12} = -\lambda_2 a_{21}$

$$a \in \begin{bmatrix} 0 & \lambda_1 \\ -\lambda_2 & 0 \end{bmatrix} \in \mathbb{C}$$

still need  $a^* = -a$

~~$(\lambda_1 z) = -\lambda_2 z$~~

$$\bar{\lambda}_1 \bar{z} = -\lambda_2 z \implies |\lambda_1| = |\lambda_2| \quad \text{unless } z=0. \quad ??$$

Go to  $LO(2n)$ . You can't have a diagonal  $b$  which is skew-symm. You probably made a bad choice  $b^* = \bar{b}^t = -b$

$$LO(2n) = \left\{ X = \begin{bmatrix} a & b \\ \bar{b} & \bar{a} \end{bmatrix} : \begin{aligned} a^* &= -a \\ b^t &= -b \end{aligned} \right\}$$

~~if~~ if  $n=2$ , then  $b = \begin{bmatrix} 0 & \lambda \\ -\lambda & 0 \end{bmatrix}$

$$(190) \quad \mathcal{L} O(2n) = \left\{ X = \begin{bmatrix} a & b \\ \bar{b} & \bar{a} \end{bmatrix} : \begin{array}{l} a^* = -a \\ b^t = -b \end{array} \right\}$$

$$n=1 \text{ have only } \left\{ \begin{bmatrix} a & 0 \\ 0 & \bar{a} \end{bmatrix} : \begin{array}{l} a \in i\mathbb{R} \\ \bar{a} = -a \end{array} \right\}$$

$$n=2 \text{ have } \left\{ \begin{bmatrix} a & b \\ \bar{b} & \bar{a} \end{bmatrix} : a \in \mathcal{L}u(2), b = \begin{bmatrix} 0 & \lambda \\ -\lambda & 0 \end{bmatrix} \right\}$$

have action  $a \# b = ab - b\bar{a}$

$$\begin{bmatrix} \alpha & \beta \\ \bar{\beta} & \bar{\alpha} \end{bmatrix} \begin{bmatrix} \gamma & \delta \\ \bar{\delta} & \bar{\gamma} \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} \bar{\alpha} & \bar{\beta} \\ \bar{\gamma} & \bar{\delta} \end{bmatrix} \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} \bar{\gamma} & \bar{\delta} \\ -\bar{\alpha} & -\bar{\beta} \end{bmatrix} \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} \bar{\delta} & -\bar{\gamma} \\ -\bar{\beta} & \bar{\alpha} \end{bmatrix}$$

$$\begin{array}{l} \bar{\alpha} = \delta \\ \bar{\beta} = -\gamma \end{array}$$

$$\therefore a = \begin{bmatrix} \alpha & \beta \\ -\bar{\beta} & \bar{\alpha} \end{bmatrix} \quad a^* = \begin{bmatrix} \bar{\alpha} & -\beta \\ \bar{\beta} & \alpha \end{bmatrix}$$

$$\bar{\alpha} = -\alpha$$

$$\therefore a = \begin{bmatrix} \alpha & \beta \\ -\bar{\beta} & \bar{\alpha} \end{bmatrix} \text{ where } \alpha + \bar{\alpha} = 0 \quad \therefore a \in \mathcal{L}su(2)$$

$$\mathcal{L}Sp(2n) = \left\{ X = \begin{bmatrix} a & b \\ -\bar{b} & \bar{a} \end{bmatrix} : \begin{array}{l} a^* = -a \\ b^t = b \end{array} \right\}$$

again the action is  $a \# b = ab - b\bar{a} = ab + b\bar{a}^t$

What's a generic  $b$ ?

General theory. You get a Cartan subalgebra as centralizer of a generic element. Rank of  $O(2n)$  should be  $n$ . Cartan subalg is  $\oplus$  of  $n$  ~~inf~~ inf rotations  $\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \omega$

(191) Look for max abelian subspace of  $\mathfrak{g}$ .

$$\begin{bmatrix} 0 & b_1 \\ \bar{b}_1 & 0 \end{bmatrix} \begin{bmatrix} 0 & b_2 \\ \bar{b}_2 & 0 \end{bmatrix} - \begin{bmatrix} 0 & b_2 \\ \bar{b}_2 & 0 \end{bmatrix} \begin{bmatrix} 0 & b_1 \\ \bar{b}_1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} b_1 \bar{b}_2 & 0 \\ 0 & \bar{b}_1 b_2 \end{bmatrix} - \begin{bmatrix} b_2 \bar{b}_1 & 0 \\ 0 & \bar{b}_2 b_1 \end{bmatrix} = \begin{bmatrix} b_1 \bar{b}_2 - b_2 \bar{b}_1 & 0 \\ 0 & \bar{b}_1 b_2 - \bar{b}_2 b_1 \end{bmatrix}$$

~~$(b_1 \bar{b}_2 - b_2 \bar{b}_1)^* = (b_1 b_2^* - b_2 b_1^*)^*$~~

$$(b\bar{c} - c\bar{b})^* + (b\bar{c} - c\bar{b}) = 0$$

$$(b\bar{c} - c\bar{b})^t = (-c)(-\bar{b}) - (-b)(-\bar{c}) = -b\bar{c} + c\bar{b}$$

want pairing  $\langle b, c \rangle = b\bar{c} - c\bar{b}$

~~Let's stop this calculation~~  
 go to Poisson brackets?

Let try to understand the picture from the creation and annihilation operator viewpoint.

$H$  has basis  $a_1, \dots, a_n, a_1^*, \dots, a_n^*$  get complex linear space of operators somewhere. Also have symplectic relation  $\{a_i, a_j^*\} = \delta_{ij}$   $\{a_i, a_j\} = 0 = \{a_i^*, a_j^*\}$

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Next you can enlarge this symplectic space by ~~symplectic prod~~  $S^2 H$ . How does this look? So far you have been using this picture

$$H = \left\{ \begin{bmatrix} x \\ y \end{bmatrix}, \begin{bmatrix} x_1 \\ y_1 \end{bmatrix}^* \begin{bmatrix} x_2 \\ y_2 \end{bmatrix}, \begin{bmatrix} x_1 \\ y_1 \end{bmatrix}^t \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ y_2 \end{bmatrix} \right\}$$

$S^2 H$  generated by ~~quadratic~~ a quadratic map

$$\begin{bmatrix} u \\ v \end{bmatrix} \longmapsto S^2 \begin{bmatrix} V \\ V^* \end{bmatrix} = S^2 V \oplus V \otimes V^* \oplus S^2 V^*$$

$$\mathcal{L} Sp(2n) = \left\{ \begin{bmatrix} a & b \\ -\bar{b} & \bar{a} \end{bmatrix} : \begin{array}{l} a^* = -a \\ b^t = b \end{array} \right\}$$

$$X = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \in \mathfrak{gl}(2n, \mathbb{C}) \quad X^t \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} + \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} X = 0$$

$$X^t = -J X J^{-1} = J X J$$

$$\begin{bmatrix} a^t & c^t \\ b^t & d^t \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} c & d \\ -a & -b \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} = \begin{bmatrix} -d & c \\ b & -a \end{bmatrix}$$

$$\therefore d = -a^t, \quad b^t = b, \quad c^t = c \quad \text{So you see } \begin{array}{ccc} S^2 V & \oplus & V \otimes V^* \oplus S^2 V^* \\ b & & \oplus a \quad c \end{array}$$

~~Suppose you replace~~

Suppose you replace  $a, b$  by bilinear expressions  
What does this mean?  $b = b_{ij}$  where  $b_{ij} = b_{ji}$

$$a_{ij} = \bar{a}_{ji}$$

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problems Max commutative subspace of  $\mathfrak{p}$ .

$$\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p} = \left\{ \begin{bmatrix} a & 0 \\ 0 & \bar{a} \end{bmatrix} : a^* = -a \right\} + \left\{ \begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix} : b^t = b \right\}$$

$$\begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix} \begin{bmatrix} 0 & c \\ -\bar{c} & 0 \end{bmatrix} = \begin{bmatrix} -b\bar{c} & 0 \\ 0 & -\bar{b}c \end{bmatrix}$$

$$\begin{bmatrix} 0 & c \\ -\bar{c} & 0 \end{bmatrix} \begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix} = \begin{bmatrix} -c\bar{b} & 0 \\ 0 & -\bar{c}b \end{bmatrix}$$

$$\begin{bmatrix} -b\bar{c} + c\bar{b} \\ -\bar{b}c + \bar{c}b \end{bmatrix}$$

$$SU(2) = Sp(2). \quad \mathcal{L}Sp(2) = \left\{ \begin{bmatrix} a & b \\ -\bar{b} & \bar{a} \end{bmatrix} : \begin{array}{l} a^* + a = 0 \text{ (means } a = i\alpha) \\ b = b^t \end{array} \right\}$$

$$\mathcal{L}SU(2) = \left\{ \begin{bmatrix} i\alpha & b \\ -\bar{b} & -i\alpha \end{bmatrix} \right\} = \left\{ x \begin{bmatrix} i & 0 \\ 0 & -i \end{bmatrix} + y \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} + z \begin{bmatrix} 0 & i \\ i & 0 \end{bmatrix} \right\}$$

$x\hat{i} + y\hat{j} + z\hat{k}$

So a maximal abelian subspace of  $\mathcal{L}SU(2)$  is 1-dim. Any ~~real~~ real lines.

~~any real lines~~

$$\begin{bmatrix} e^{i\alpha} & 0 \\ 0 & e^{-i\alpha} \end{bmatrix} \begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix} \begin{bmatrix} e^{-i\alpha} & 0 \\ 0 & e^{+i\alpha} \end{bmatrix} = \begin{bmatrix} 0 & e^{2i\alpha}b \\ -\bar{b}e^{-2i\alpha} & 0 \end{bmatrix}$$

Clear you have conjugacy for the maximal abelian subspaces.

Consider next example ~~mathcal{L}SO(2n)~~  $\mathcal{L}SO(2n) \quad n=2$

$$\mathcal{L}SO(2n) = \mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p} = \left\{ \begin{bmatrix} a & 0 \\ 0 & \bar{a} \end{bmatrix} : a^* = -a \right\} \oplus \left\{ \begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix} : b^t = -b \right\}$$

$$\begin{bmatrix} a & 0 \\ 0 & \bar{a} \end{bmatrix} \begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix} - \begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix} \begin{bmatrix} a & 0 \\ 0 & \bar{a} \end{bmatrix} = \begin{bmatrix} 0 & ab \\ \bar{a}\bar{b} & 0 \end{bmatrix} - \begin{bmatrix} 0 & b\bar{a} \\ \bar{b}a & 0 \end{bmatrix} = \begin{bmatrix} 0 & ab - b\bar{a} \\ \bar{a}\bar{b} - \bar{b}a & 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix} \begin{bmatrix} 0 & c \\ \bar{c} & 0 \end{bmatrix} - \begin{bmatrix} 0 & c \\ \bar{c} & 0 \end{bmatrix} \begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix} = \begin{bmatrix} b\bar{c} & 0 \\ 0 & \bar{b}c \end{bmatrix} - \begin{bmatrix} c\bar{b} & 0 \\ 0 & \bar{c}b \end{bmatrix} = \begin{bmatrix} b\bar{c} - c\bar{b} & 0 \\ 0 & \bar{b}c - \bar{c}b \end{bmatrix}$$

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Checks  $(b\bar{c} - c\bar{b})^t = \cancel{c^t b^t} - \bar{b}^t c^t = \bar{c}b - \bar{b}c$

$(b\bar{c} - c\bar{b})^* = c\bar{b} - b\bar{c} \checkmark$

$$\begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix}^* = \begin{bmatrix} 0 & \bar{b}^* \\ b^* & 0 \end{bmatrix} = \begin{bmatrix} 0 & b^t \\ \bar{b}^t & 0 \end{bmatrix} = \begin{bmatrix} 0 & -b \\ -\bar{b} & 0 \end{bmatrix} = - \begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix}$$

So now you want  $n=2$   $b = \begin{bmatrix} 0 & \lambda \\ -\lambda & 0 \end{bmatrix}$   $c = \begin{bmatrix} 0 & \mu \\ -\mu & 0 \end{bmatrix}$

~~check~~

$$\begin{aligned} b\bar{c} - c\bar{b} &= \begin{bmatrix} 0 & \lambda \\ -\lambda & 0 \end{bmatrix} \begin{bmatrix} 0 & \bar{\mu} \\ -\bar{\mu} & 0 \end{bmatrix} - \begin{bmatrix} 0 & \mu \\ -\mu & 0 \end{bmatrix} \begin{bmatrix} 0 & \bar{\lambda} \\ -\bar{\lambda} & 0 \end{bmatrix} \\ &= \begin{bmatrix} -\lambda\bar{\mu} & 0 \\ 0 & -\lambda\bar{\mu} \end{bmatrix} - \begin{bmatrix} -\mu\bar{\lambda} & 0 \\ 0 & -\mu\bar{\lambda} \end{bmatrix} \quad \begin{matrix} \rightarrow \\ \end{matrix} \begin{matrix} -\lambda & \bar{\lambda} \\ \mu & \bar{\mu} \end{matrix} \\ &= \begin{bmatrix} -\lambda\bar{\mu} + \mu\bar{\lambda} & 0 \\ 0 & -\lambda\bar{\mu} + \mu\bar{\lambda} \end{bmatrix} = (-\lambda\bar{\mu} + \mu\bar{\lambda}) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \end{aligned}$$

So the symplectic space has rank 1: ~~any~~ maximal abelian subspace in  $\mathfrak{p}$  is 1 dim.

Count dims.  $\dim \mathfrak{k} = 4$ ,  $\dim \mathfrak{p} = 2$  have  $\mathfrak{k}$  acting on  $\mathfrak{p}$ :  $a \# b = ab - b\bar{a}$ . There is a structure here that you don't understand. 4 dim compact lie group acting on a complex line.

~~check~~

$$\left[ \begin{bmatrix} a & 0 \\ 0 & \bar{a} \end{bmatrix}, \begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix} \right] = \begin{bmatrix} 0 & ab - b\bar{a} \\ \bar{a}b - b\bar{a} & 0 \end{bmatrix} \quad a \# b = ab - b\bar{a}$$

Take  $b = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$

$$\underbrace{\begin{bmatrix} \alpha & \beta \\ \gamma & \delta \end{bmatrix}}_a \underbrace{\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}}_b - \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \underbrace{\begin{bmatrix} \bar{\alpha} & \bar{\beta} \\ \bar{\gamma} & \bar{\delta} \end{bmatrix}}_b = \begin{bmatrix} -\beta & \alpha \\ -\delta & \gamma \end{bmatrix} - \begin{bmatrix} \bar{\gamma} & \bar{\delta} \\ -\bar{\alpha} & -\bar{\beta} \end{bmatrix}$$

So get:  $a \# b = 0 \Leftrightarrow \bar{\gamma} = -\beta, \delta = \bar{\alpha}$

$a^* + a = 0$  means  $\alpha + \bar{\alpha} = 0, \gamma = -\bar{\beta}, \delta + \bar{\delta} = 0$ . Conclude

that  $a = \begin{bmatrix} it & \beta \\ -\bar{\beta} & -it \end{bmatrix} \quad \underbrace{t \in \mathbb{R}}_{i.e.} \quad a \in \mathfrak{su}(2)$ .

(195) A better way to see this is to use  
 $u \# b = ubu^t = ub\bar{u}^{-1}$  If ~~that~~  $ubu^t = b$

then  $(\det u)^2 \det b = \det b \therefore \det(u) = \pm 1$ . So

infinitesimally  $\text{tr}(a) = 0$ . Better:  $ab = b\bar{a} \Rightarrow$

$$\text{tr}(ab) = \text{tr}(b\bar{a}) = \text{tr}(\bar{a}b) \Rightarrow \text{tr}((a-\bar{a})b) = 0$$

$a-\bar{a}$  = purely imag skew adj.  $\therefore a-\bar{a} = ih$ , <sup>real</sup>  $h$  ~~symm.~~  $h$  ~~symm.~~

$h$  ~~symm.~~  $b = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$  skew-symm.  $\therefore \text{tr}(hb) = 0$

So in the case of  $SO(2n)$ ,  $n=2$  You get

$U(2)$  acting on  $\Lambda^2 \mathbb{C}^2$ , the kernel must be  $SU(2)$ ,  
 of the action on this line is via the determinant.

Next case is  $Sp(2n)$ ,  $n=2$ .  $X = \begin{bmatrix} a & b \\ -\bar{b} & \bar{a} \end{bmatrix}$ :  $a^x = -a$   
 $b^t = +b$

Action  $\begin{bmatrix} u & 0 \\ 0 & \bar{u} \end{bmatrix} \begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix} \begin{bmatrix} u^x & 0 \\ 0 & u^t \end{bmatrix} = \begin{bmatrix} ubu^t & 0 \\ 0 & -\bar{u}b\bar{u}^x \end{bmatrix}$

Inf. action  $a \# b = ab - b\bar{a} = ab + ba^t$ . You have  
 the action of  $u \in U(n)$  on ~~the space of~~  $\{b : b^t = b\}$

= symmetric bilinear forms, usual action  $u \# b = ubu^t$

Now if  $n=2$ , then  $b$  should be the same as  
 a quadratic form on  $\mathbb{C}^n$ , the space is 3 dim /  $\mathbb{C}$   
 and the corresponding projective space <sup>(should be)</sup> the Riemann  
 sphere  $S^2$ . You want to identify ~~maps~~ the complex  
 lines in  $S^2(\mathbb{C})$  with degree 2 positive divisors on  $S^2$ ,  
 and  $U(2)$  should be acting by orthogonal rotations  
 on  $S^2$ . Count dims  $Sp(4)$  has <sup>real</sup> dim  $2^2 + 2(3) = 10$ .

~~U(2)~~  $U(2)$  acting on  $S^2 \mathbb{C}^2$ . It looks like the  
 scalar matrices in  $U(2)$  map onto the scalar operators  
 on  $S^2 \mathbb{C}^2$ . It seems that the interesting action is

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$SU(2)$  rotations on degree 2 divisors

on  $S^2$ .

~~There's~~ There's one invariant here, namely,  $\cos \theta$  where  $\theta$  is the  $\angle$  between the 2 pts of the divisor.

Puzzle:  $U(2)$  acting on  $S^2 \mathbb{C}^2 \simeq \mathbb{C}^3$ , yield

$SU(2)$  acting on  $\mathbb{P}(S^2 \mathbb{C}^2) \simeq S^2$

Situation  $V$  complex v.s. with pos herm. form

say  $V = \mathbb{C}^n$  with  $\langle x, y \rangle = x^* y$ . Suppose also given  $b^t = b$ . Then you have a quadratic function  $\frac{1}{2} x^t b x$ . The obvious thing to do is to maximise  $\frac{1}{2} x^t b x$  subject to  $x^* x = 1$

$$F(x) = \frac{1}{2} x^t b x + \lambda \left( \frac{1}{2} x^* x - 1 \right)$$

except  $\frac{1}{2} x^t b x$  is not real valued

~~What is the~~ Go back to

$$F(u) = \frac{1}{2} \text{tr} \left( g p g^{-1} - p_0 \right)^2$$

$$= \frac{1}{2} \text{tr} (g p^2) + \frac{1}{2} \text{tr} (p_0^2) - \text{tr} (g p g^{-1} p_0)$$

assume  $g=1$  is critical point for  $F$ .

$$\forall X \quad 0 = \text{tr} ([X, p] p_0) = \text{tr} (X [p, p_0]) \implies [p, p_0] = 0$$

$$\text{Sp}(2n) \quad g = \begin{bmatrix} a & 0 \\ 0 & \bar{a} \end{bmatrix} \quad p = \begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix} \quad b^t = b.$$

Want  $p_0$  chosen so that its centralizer is max ab.

~~When~~  $n=2$   $g = k \oplus p$

$$\begin{bmatrix} a & 0 \\ 0 & \bar{a} \end{bmatrix} \oplus \begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix}$$



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simple calculations.

$$P_0 = \left[ \begin{array}{c|c} 0 & b \\ \hline +\bar{b} & 0 \end{array} \right]$$

$$b^t = -b$$

centralizer of  $P_0$  where  $b$  is something easy. First case

$$b = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

$$\left[ \left[ \begin{array}{c|c} a & \\ \hline & \bar{a} \end{array} \right], \left[ \begin{array}{c|c} b & \\ \hline & \bar{b} \end{array} \right] \right] = \left[ \begin{array}{c|c} 0 & ab - \bar{b}\bar{a} \\ \hline +\bar{a}\bar{b} - \bar{b}a & 0 \end{array} \right]$$

$$\begin{bmatrix} \alpha & \beta \\ \gamma & \delta \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} - \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} \bar{\alpha} & \bar{\beta} \\ \bar{\gamma} & \bar{\delta} \end{bmatrix} = \begin{bmatrix} -\beta & \alpha \\ -\delta & \gamma \end{bmatrix} - \begin{bmatrix} \bar{\gamma} & \bar{\delta} \\ -\bar{\alpha} & -\bar{\beta} \end{bmatrix}$$

$a \quad b$

$b \quad \bar{a}$

$$\delta = \bar{\alpha}, \alpha = \bar{\delta}$$

$$\gamma = -\bar{\beta}, \beta = -\bar{\gamma}$$

$$a^* = -a \Rightarrow \gamma = -\bar{\beta}, \bar{\alpha} = -\alpha, \bar{\delta} = -\delta$$

$$\alpha = it, \beta = -it$$

$$a = \begin{bmatrix} it & \beta \\ -\bar{\beta} & -it \end{bmatrix}$$

trace 0

~~But we see that~~

~~Had~~

$$\left[ \left[ \begin{array}{c|c} p_0 & b \\ \hline \bar{b} & 0 \end{array} \right], \left[ \begin{array}{c|c} 0 & c \\ \hline \bar{c} & 0 \end{array} \right] \right] = \left[ \begin{array}{c|c} b\bar{c} - c\bar{b} & 0 \\ \hline 0 & -\bar{c}b + \bar{b}c \end{array} \right]$$

Perhaps try  $\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$

Ask about centralizer. What you want is a ~~centralizer~~

$$P_0 = \begin{bmatrix} 0 & b \\ +\bar{b} & 0 \end{bmatrix} \quad b^t = -b \quad \text{with a small centralizer.}$$

Basic observation is that you need 2 planes.

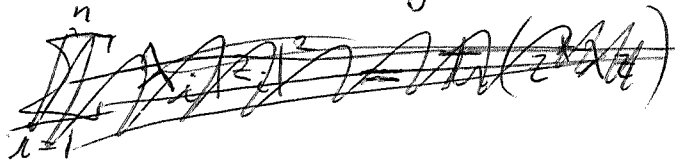
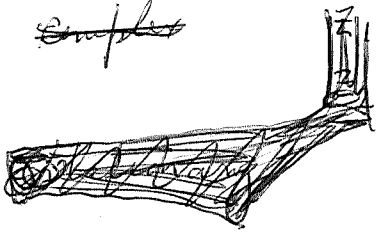
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Basically you would like to start with ~~finite dimensional Hilbert space~~ a complex space  $V$  equipped with pos. herm. form, then add a ~~symmetric~~ symmetric  $\mathbb{C}$  linear form.

$n=1$ . Given  $\mathbb{C}$  with  $x^*x$  and a symm form  $ax^2$ . Obvious invariant, namely  $|a| = |ax^2|$  when  $|x|=1$ .

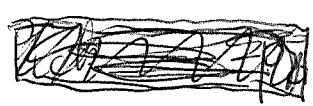
$n=2$ .  $\mathbb{C}^2$  idea is to ~~compute invariants~~ look at ~~all~~ all  $L \subset \mathbb{C}^2$

Morse theory for  $\mathbb{C}P^n$ . Something like height ~~simple~~



$$\sum \lambda_i z_i ?$$

Use method you know, ~~which~~ which involves  $U(n)$  acting by conjugation on hermitian matrices.



$$gpg^* -$$

Point of  $\mathbb{C}P^{n-1}$  is a hermitian projection of rank 1. ~~Then~~ Then take any ~~hermitian op.~~ hermitian op.  $A$  and use the trace. So the ~~Morse~~ Morse function amounts to contracting  $i^*A \cup$ ,  $i: L \hookrightarrow \mathbb{C}^n$

Method: Let  $A$  be a hermitian operator on  $\mathbb{C}^n$ . Then  $x^*Ax$  ~~for~~ for  $|x|=1$  descends to a <sup>real</sup> function on  $PC^n$ . Assume  $x \in \mathbb{C}$  is a stationary point and let  $\delta x$  be any variation preserving  $x^*x=1$  to first order:  $\delta x^*x = 0$ . Then

$$0 = (\delta x)^*Ax + x^*A\delta x = 2(\delta x)^*Ax$$

(199) But  $(\delta x)^* A x = 0$  for all  $\delta x \perp x$  implies  $Ax = \lambda x$ ;  $\lambda \in \mathbb{C}$ ; then  $\lambda \in \mathbb{R}$  because  $A$  hermitian.

Next you want to handle  $\mathbb{L} Sp(2n)$  with  $n=2$ .  
 $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}$   
 $n^2 + 2\left(\frac{n(n+1)}{2}\right)$   $\left\{ \begin{bmatrix} a & 0 \\ 0 & \bar{a} \end{bmatrix} \right\} \left\{ \begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix} \right\}$   $a^* = -a$   
 $b^t = b$ .

$$a \# b = ab + ba^t = ab - b\bar{a}$$

Why look <sup>first</sup> at this case? Instead take  $\mathbb{L} O(2n)$  with  $n=2$ .  
 $n^2 + n(n-1)$   $\mathfrak{g} = \left\{ \begin{bmatrix} a & 0 \\ 0 & \bar{a} \end{bmatrix} : a^* + a = 0 \right\} \oplus \left\{ \begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix} : b^t = -b \right\}$

$$b = \lambda \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}, \lambda \in \mathbb{C} \quad \text{Let } a = \begin{bmatrix} i s & \beta \\ -\bar{\beta} & i t \end{bmatrix} \quad \begin{matrix} s, t \in \mathbb{R} \\ \beta \in \mathbb{C} \end{matrix}$$

$$\begin{bmatrix} i s & \beta \\ -\bar{\beta} & i t \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} = \begin{bmatrix} -\beta & i s \\ -i t & -\bar{\beta} \end{bmatrix}$$

$$u \in U(2)$$

$$u \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} u^t = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} -i s & \bar{\beta} \\ -\beta & -i t \end{bmatrix} = \begin{bmatrix} -\beta & -i t \\ i s & -\bar{\beta} \end{bmatrix}$$

$$u = \begin{bmatrix} \alpha & \beta \\ \gamma & \delta \end{bmatrix} \in U(2) \quad \begin{matrix} \alpha^t = \alpha \\ \delta^t = \delta \\ \beta^t = -\gamma \\ \gamma^t = -\beta \end{matrix}$$

$$u J \bar{u}^{-1} = J$$

$$u J = J \bar{u}$$

$$u = -J \bar{u} J$$

$$\begin{bmatrix} \alpha & \beta \\ \gamma & \delta \end{bmatrix} = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} \bar{\alpha} & \bar{\beta} \\ \bar{\gamma} & \bar{\delta} \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

$$u = \begin{bmatrix} \alpha & \beta \\ -\bar{\beta} & \bar{\alpha} \end{bmatrix}$$

$$= \begin{bmatrix} -\bar{\gamma} & -\bar{\delta} \\ \bar{\alpha} & \bar{\beta} \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} = \begin{bmatrix} \bar{\delta} & -\bar{\gamma} \\ -\bar{\beta} & \bar{\alpha} \end{bmatrix}$$

$$|\alpha|^2 + |\beta|^2 = 1$$

$$\det(u) = 1$$

~~...~~

200 What have you learned? Just that the action  $u \cdot b = ubu^t$  on  $b = J$  seems to involve only the determinant of  $u$ .

Go over this again. You <sup>have</sup>  $b = \lambda \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$   $\lambda \in \mathbb{C}$ .

acted on by  $u \in U(2)$  via  $u \cdot b = ubu^t = ub\bar{u}^{-1}$ .

The action is  $\mathbb{C}$  linear on the  $\mathbb{C}$ -line  $\{b\}$ , so it's via a character of  $U(2)$ . Let  $u = \begin{bmatrix} \alpha & \beta \\ \gamma & \delta \end{bmatrix} \in U(2)$ .

You ~~want~~ want

$$\begin{aligned} u J u^t &= \begin{bmatrix} \alpha & \beta \\ \gamma & \delta \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} \alpha & \gamma \\ \beta & \delta \end{bmatrix} = \begin{bmatrix} -\beta & \alpha \\ -\delta & \gamma \end{bmatrix} \begin{bmatrix} \alpha & \gamma \\ \beta & \delta \end{bmatrix} \\ &= \begin{bmatrix} 0 & \alpha\delta - \beta\gamma \\ -\alpha\delta + \beta\gamma & 0 \end{bmatrix} = \det(u) J \end{aligned}$$

$\therefore$  The centralizer of  $J$  in  $U(2)$  is  $SU(2)$ .

This handles the case of  $k \oplus \mathfrak{p}$  for  $LSO(4)$ .

Next case is  $LSp(4) = \left\{ \begin{bmatrix} a & 0 \\ 0 & \bar{a} \end{bmatrix} : a^* = -a \right\} \oplus \left\{ \begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix} : b^t = b \right\}$

In this case  $k$  has real dim 4,  $\mathfrak{p}$  has real dim 6.

Recall  $LSp(2) = \left\{ \begin{bmatrix} it & \beta \\ -\bar{\beta} & -it \end{bmatrix} : t \in \mathbb{R}, \beta \in \mathbb{C} \right\}$ . Then

action of ~~u~~  $u = e^{it}$  on  $\beta$  is  $e^{it} \cdot \beta = e^{2it} \beta$ .

Viewpoint: You want to classify symmetric bilinear forms on a <sup>complex</sup> vector space equipped with a positive hermitian form. What approaches to use?

- 1) Polar decomposition
- 2) Find a maximal abelian subspace of  $\mathfrak{p}$ , which probably is the ~~centralizer~~ centralizer of a generic element.

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$n=2$

$$b = \begin{bmatrix} x & y \\ y & z \end{bmatrix}$$

You want a

~~maximal abelian subspace~~ a maximal abelian subspace

$$\text{of } \mathfrak{p} = \left\{ \begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix} : b^t = b \right\}$$

$$\begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix} \begin{bmatrix} 0 & c \\ -\bar{c} & 0 \end{bmatrix} - \begin{bmatrix} 0 & c \\ -\bar{c} & 0 \end{bmatrix} \begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix}$$

$$\begin{bmatrix} -b\bar{c} & 0 \\ 0 & -\bar{b}c \end{bmatrix} - \begin{bmatrix} -c\bar{b} & 0 \\ 0 & -\bar{c}b \end{bmatrix} = \begin{bmatrix} -b\bar{c} + c\bar{b} & 0 \\ 0 & -\bar{b}c + \bar{c}b \end{bmatrix}$$

Check this lies in  $\mathfrak{k}$ .

$$a = -b\bar{c} + c\bar{b}$$

$$a^* = -\bar{c}^* b^* + b^* c^* = -c\bar{b} + b\bar{c} = -a$$

~~My~~ This calculation works for any  $n$ , e.g.  $n=1$ .

where you are getting  $-b\bar{c} + c\bar{b} = 2i \operatorname{Im}(c\bar{b})$ ?

$$\operatorname{Im}(c\bar{b}) = \operatorname{Im}((c_1 + ic_2)(b_1 - ib_2)) = c_2 b_1 - c_1 b_2$$

$$\frac{c\bar{b} - \bar{c}b}{2i}$$

You want something like

$$b = \begin{bmatrix} \cdot & \cdot \\ \cdot & \cdot \end{bmatrix}$$

$$b = \begin{bmatrix} x & y \\ y & z \end{bmatrix}$$

$$c = \begin{bmatrix} \xi & \eta \\ \eta & \zeta \end{bmatrix}$$

Find  $-b\bar{c} + c\bar{b}$

$$- \begin{bmatrix} x & y \\ y & z \end{bmatrix} \begin{bmatrix} \bar{\xi} & \bar{\eta} \\ \bar{\eta} & \bar{\zeta} \end{bmatrix} = - \begin{bmatrix} x\bar{\xi} + y\bar{\eta} & x\bar{\eta} + y\bar{\zeta} \\ y\bar{\xi} + z\bar{\eta} & y\bar{\eta} + z\bar{\zeta} \end{bmatrix}$$

$$+ \begin{bmatrix} \xi & \eta \\ \eta & \zeta \end{bmatrix} \begin{bmatrix} \bar{x} & \bar{y} \\ \bar{y} & \bar{z} \end{bmatrix} = \begin{bmatrix} \xi\bar{x} + \eta\bar{y} & \xi\bar{y} + \eta\bar{z} \\ \eta\bar{x} + \zeta\bar{y} & \eta\bar{y} + \zeta\bar{z} \end{bmatrix}$$

$$b = \begin{bmatrix} x & 0 \\ 0 & 0 \end{bmatrix} \quad c = \begin{bmatrix} \xi & \eta \\ \eta & \zeta \end{bmatrix}$$

$$-b\bar{c} + c\bar{b} = - \begin{bmatrix} x\bar{\xi} & x\bar{\eta} \\ 0 & 0 \end{bmatrix} + \begin{bmatrix} \xi\bar{x} & 0 \\ \eta\bar{x} & 0 \end{bmatrix} = \begin{bmatrix} -x\bar{\xi} + \xi\bar{x} & -x\bar{\eta} \\ \eta\bar{x} & 0 \end{bmatrix}$$

Therefore the centralizer of  $\begin{bmatrix} x & 0 \\ 0 & 0 \end{bmatrix}$  is  $\begin{bmatrix} \mathbb{R}x & 0 \\ 0 & \mathbb{C} \end{bmatrix}$  ( $x \neq 0$ )

Next  $b = \begin{bmatrix} 0 & 0 \\ 0 & z \end{bmatrix}$

$$-bc + c\bar{b} = - \begin{bmatrix} 0 & 0 \\ z\bar{\eta} & z\bar{\xi} \end{bmatrix} + \begin{bmatrix} 0 & \eta\bar{z} \\ 0 & \xi\bar{z} \end{bmatrix} = \begin{bmatrix} 0 & \eta\bar{z} \\ -z\bar{\eta} & -z\bar{\xi} + \xi\bar{z} \end{bmatrix}$$

The centralizer of  $\begin{bmatrix} 0 & 0 \\ 0 & z \end{bmatrix}$  is  $\begin{bmatrix} \mathbb{C} & 0 \\ 0 & \mathbb{R}z \end{bmatrix}$

cent of  $\begin{bmatrix} 0 & y \\ y & 0 \end{bmatrix}$

$$- \begin{bmatrix} y\bar{\eta} & y\bar{\xi} \\ y\bar{\xi} & y\bar{\eta} \end{bmatrix} + \begin{bmatrix} \eta\bar{y} & \xi\bar{y} \\ \xi\bar{y} & \eta\bar{y} \end{bmatrix}$$

$$= \begin{bmatrix} -y\bar{\eta} + \eta\bar{y} & -y\bar{\xi} + \xi\bar{y} \\ -y\bar{\xi} + \xi\bar{y} & -y\bar{\eta} + \eta\bar{y} \end{bmatrix} = 0 \quad \text{when } y \in \mathbb{R}y \quad \text{and } y\bar{\xi} = \xi\bar{y}$$

What does  $y\bar{\xi} = \xi\bar{y}$  mean?  
 $\xi = \bar{\xi}$ . So centralizer is

Say  $y$  real  $\neq 0$ , says  $c = \begin{bmatrix} \xi & t \\ t & \bar{\xi} \end{bmatrix}$



where  $\xi \in \mathbb{C}$  and  $t \in \mathbb{R}$ .

There should be better ways to calculate the centralizers. What do these  $b$  matrices mean?

	$n=1$	$n=2$	$n=3$	
$SO(2n)$	0	2	6	table gives real dim of space of $b$ matrices
$Sp(2n)$	2	6		

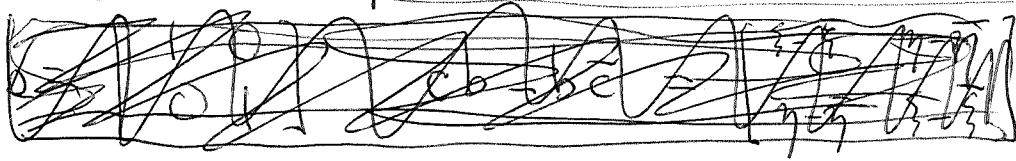
~~What you want to understand~~ What you want to understand is the  $U(n)$  action on the space of ~~symmetric~~ symmetric  $\mathbb{C}$  bilinear forms.

203 Do calculations in simple cases

$$b = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \quad c = \begin{bmatrix} \xi & \eta \\ \eta & \zeta \end{bmatrix}$$

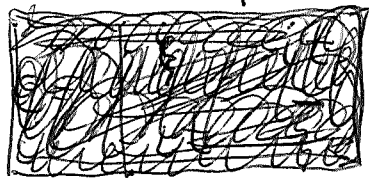
$$-b\bar{c} + cb = cb - b\bar{c} = \begin{bmatrix} \xi & 0 \\ \eta & 0 \end{bmatrix} - \begin{bmatrix} \bar{\xi} & \bar{\eta} \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} \xi - \bar{\xi} & -\bar{\eta} \\ \eta & 0 \end{bmatrix}$$

$$\therefore \xi = \bar{\xi}, \eta = 0, \zeta \in \mathbb{C}. \quad c = \begin{bmatrix} \xi & 0 \\ 0 & \zeta \end{bmatrix} : \xi \in \mathbb{R}, \zeta \in \mathbb{C}$$



$$b = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \quad cb - b\bar{c} = \begin{bmatrix} \xi & \eta \\ \eta & \zeta \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} - \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} \bar{\xi} & \bar{\eta} \\ \bar{\eta} & \bar{\zeta} \end{bmatrix}$$

$$= \begin{bmatrix} \eta & \xi \\ \zeta & \eta \end{bmatrix} - \begin{bmatrix} \bar{\eta} & \bar{\zeta} \\ \bar{\xi} & \bar{\eta} \end{bmatrix} = \begin{bmatrix} \eta - \bar{\eta} & \xi - \bar{\zeta} \\ \zeta - \bar{\xi} & \eta - \bar{\eta} \end{bmatrix} \quad \text{whence}$$



$b$  centralizes  $c$  iff  $\eta \in \mathbb{R}, \zeta = \bar{\xi}, \xi \in \mathbb{C}$

$$c = \begin{bmatrix} \xi & t \\ t & \bar{\xi} \end{bmatrix} \quad t \in \mathbb{R}, \xi \in \mathbb{C}.$$

$$b = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} \xi & \eta \\ \eta & \zeta \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} - \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} \bar{\xi} & \bar{\eta} \\ \bar{\eta} & \bar{\zeta} \end{bmatrix} = \begin{bmatrix} 0 & \eta \\ -\bar{\eta} & \zeta - \bar{\zeta} \end{bmatrix}$$

$$c \text{ centralizes } b \Leftrightarrow \eta = 0, \zeta \in \mathbb{R} \quad \text{i.e.} \quad c = \begin{bmatrix} \xi & 0 \\ 0 & t \end{bmatrix} \quad \begin{matrix} \xi \in \mathbb{C} \\ t \in \mathbb{R} \end{matrix}$$

You should need now a root calculation only. Go back to  $\mathfrak{L} \diamond SO(2n) = \left\{ \begin{bmatrix} a & 0 \\ 0 & \bar{a} \end{bmatrix} : a^* = -a \right\} \oplus \left\{ \begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix}, \begin{matrix} b \in \mathbb{H} \\ -b \end{matrix} \right\}$

Take  $n=3$ .  $b = \begin{bmatrix} 0 & x & y \\ -x & 0 & z \\ -y & -z & 0 \end{bmatrix}$

Let's review the conjugacy argument. You have  $P, P_0 \in \mathfrak{p}$

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You want a maximal abelian subspace of  $\mathfrak{p}$ . You have  $b = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$  ~~commuting~~ commuting with

$$c = \begin{bmatrix} \xi & 0 \\ 0 & \zeta \end{bmatrix} \quad \forall \xi \in \mathbb{R}, \zeta \in \mathbb{C}.$$

It seems that  $\mathfrak{a} = \left\{ b = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}; \lambda_1, \lambda_2 \in \mathbb{R} \right\}$

is a maximal abelian subspace of  $\mathfrak{p} = \left\{ \begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix}; b^t = b \right\}$ ,

because the centralizer ~~in~~ in  $\mathfrak{p}$  of  $\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$  is  $\begin{bmatrix} \mathbb{R} & 0 \\ 0 & \mathbb{C} \end{bmatrix}$

$$\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \text{ is } \begin{bmatrix} \mathbb{C} & 0 \\ 0 & \mathbb{R} \end{bmatrix}$$

Try extending to  $Sp(2n)$ ,  $n=3$ .

$$b = \begin{bmatrix} 1 & 0 & 0 \\ 0 & & \\ 0 & & \end{bmatrix} \quad c = \begin{bmatrix} p & q & r \\ q & r & s \\ r & s & t \end{bmatrix}$$

$$cb - b\bar{c} = \begin{bmatrix} p & 0 & 0 \\ q & 0 & 0 \\ r & 0 & 0 \end{bmatrix} - \begin{bmatrix} \bar{p} & \bar{q} & \bar{r} \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} p - \bar{p} & -\bar{q} & -\bar{r} \\ q & 0 & 0 \\ r & 0 & 0 \end{bmatrix}$$

$$\text{Cent} \begin{bmatrix} 1 & 0 & 0 \\ 0 & & \\ 0 & & \end{bmatrix} = \left\{ \begin{bmatrix} \mathbb{R} & 0 & 0 \\ 0 & r & s \\ 0 & s & t \end{bmatrix}; r, s, t \in \mathbb{C} \right\} \quad \begin{array}{l} \text{obviously} \\ \text{works for} \\ \text{general } n \end{array}$$

back to  $SO(2n)$ ,  $n=1$ . ~~back to  $SO(2n)$ ,  $n=1$ .~~

$$\mathfrak{so} = \mathfrak{L}SO(2n) = \left\{ \begin{bmatrix} a & 0 \\ 0 & \bar{a} \end{bmatrix}; \bar{a} = -a \right\} \oplus \left\{ \begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix}; b^t = -b \right\}$$

$$n=2 \quad \mathfrak{so} = \left\{ \begin{bmatrix} a & | \\ | & \bar{a} \end{bmatrix}; a^* = -a \right\} \oplus \left\{ \begin{bmatrix} 0 & | & b \\ | & & \\ \bar{b} & | & 0 \end{bmatrix}; b^t = -b \right\}.$$

$$b = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \quad c = \begin{bmatrix} 0 & q \\ -q & 0 \end{bmatrix}$$



$$\begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix} \begin{bmatrix} 0 & c \\ \bar{c} & 0 \end{bmatrix} = \begin{bmatrix} b\bar{c} & 0 \\ 0 & \bar{b}c \end{bmatrix}$$

$$\begin{bmatrix} 0 & c \\ \bar{c} & 0 \end{bmatrix} \begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix} = \begin{bmatrix} c\bar{b} & 0 \\ 0 & \bar{c}b \end{bmatrix}$$

$$\begin{aligned} & (b\bar{c} - c\bar{b})^* \\ &= \bar{c}^* b^* - b^* c^* \\ &= c^t \bar{b}^t - b^t \bar{c}^t \\ &= c\bar{b} - b\bar{c} \end{aligned}$$

$$\left[ \begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix}, \begin{bmatrix} 0 & c \\ \bar{c} & 0 \end{bmatrix} \right] = \begin{bmatrix} b\bar{c} - c\bar{b} & 0 \\ 0 & \bar{b}c - \bar{c}b \end{bmatrix}$$

$$b\bar{c} - c\bar{b} \quad \text{when } b = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \quad c = \begin{bmatrix} 0 & g \\ -\bar{g} & 0 \end{bmatrix}$$

$$b\bar{c} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} 0 & \bar{g} \\ -\bar{g} & 0 \end{bmatrix} = \begin{bmatrix} -\bar{g} & 0 \\ 0 & -\bar{g} \end{bmatrix}$$

$$\begin{matrix} -\bar{g} + g & \\ & -\bar{g} + g \end{matrix}$$

$$c\bar{b} = \begin{bmatrix} 0 & g \\ -\bar{g} & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} = \begin{bmatrix} -\bar{g} & 0 \\ 0 & -\bar{g} \end{bmatrix}$$

$$b\bar{c} - c\bar{b} = - \begin{bmatrix} g + \bar{g} & 0 \\ 0 & g + \bar{g} \end{bmatrix}$$

$$b\bar{c} - c\bar{b} = 0 \Leftrightarrow g + \bar{g} = 0$$

i.e.  $g$  real

~~Matrix representing for  $so(4)$  is  $2 \times 2$  to  $2 \times 2$~~

It seems that ~~if~~ if  $g + \bar{g} = 0$ , then

$$\begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

$$\text{and } \begin{bmatrix} 0 & c \\ \bar{c} & 0 \end{bmatrix} = \begin{bmatrix} 0 & g \\ -\bar{g} & 0 \end{bmatrix}$$

Commutate.

Repeat:  $LSO(2n)$   $\begin{bmatrix} a & b \\ \bar{b} & a \end{bmatrix}$ :  $a^* = -a$   
 $b^t = -b$

$$n=2 \Rightarrow b = \lambda \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

Take  $b = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$ ,  $c = \begin{bmatrix} 0 & g \\ -\bar{g} & 0 \end{bmatrix}$  where  $g \in \mathbb{C}$ .

$$\left[ \begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix}, \begin{bmatrix} 0 & c \\ \bar{c} & 0 \end{bmatrix} \right] = \begin{bmatrix} b\bar{c} - \bar{b}c & 0 \\ 0 & \bar{b}c - c\bar{b} \end{bmatrix}$$

206 need  $b\bar{c} - \bar{b}c = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} 0 & \bar{g} \\ -\bar{g} & 0 \end{bmatrix}$

$$b\bar{c} - \bar{b}c = b(\bar{c} - c)$$

$$= \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} 0 & \bar{g} - g \\ -\bar{g} + g & 0 \end{bmatrix} \quad \left( \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} 0 & g \\ -g & 0 \end{bmatrix} \right)$$

$$= \begin{bmatrix} -g + \bar{g} & 0 \\ 0 & g - \bar{g} \end{bmatrix}$$

so  $\begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix}$  and  $\begin{bmatrix} 0 & c \\ \bar{c} & 0 \end{bmatrix}$  commute iff  $g = \bar{g}$   
i.e.  $g \in \mathbb{R}$ .

Let's return to conjugacy thm. Consider  $\mathcal{L} Sp(2n) = \left\{ \begin{bmatrix} a & b \\ -\bar{b} & \bar{a} \end{bmatrix} : \begin{matrix} a^* = -a \\ b^t = b \end{matrix} \right\}$  and consider

$$b = \begin{bmatrix} & & & 1 \\ & & & 0 \\ & & & \dots \\ & & & 0 \end{bmatrix}$$

better:

$$\begin{bmatrix} & & & 1 \\ & & & 0 \\ & & & \dots \\ & & & 0 \\ -1 & & & \end{bmatrix} = P_0$$

You want to find all  $p = \begin{bmatrix} 0 & c \\ -\bar{c} & 0 \end{bmatrix}$

commuting with  $P_0$ . ~~find all~~ This means

finding all  $c = c^t$  such that ~~is~~

$$\begin{bmatrix} & b \\ -\bar{b} & \end{bmatrix} \begin{bmatrix} & c \\ -\bar{c} & \end{bmatrix} = \begin{bmatrix} -b\bar{c} & \\ & -\bar{b}c \end{bmatrix}$$

$$\begin{bmatrix} & c \\ -\bar{c} & \end{bmatrix} \begin{bmatrix} & b \\ -\bar{b} & \end{bmatrix} = \begin{bmatrix} -c\bar{b} & \\ & -\bar{c}b \end{bmatrix}$$

$$\begin{bmatrix} -b\bar{c} + c\bar{b} & \\ & -\bar{b}c + \bar{c}b \end{bmatrix}$$



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Restrict to  $\sum_{i=1}^n |z_i|^2 = 1$ Consider  $LSO(\mathbb{R}^n) = \mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p} = \left\{ \begin{bmatrix} a & b \\ \bar{b} & a \end{bmatrix} : \begin{matrix} a^t = -a \\ b^t = -b \end{matrix} \right\}$ 

$$b_0 = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

$$p_0 = \begin{bmatrix} 0 & b_0 \\ b_0 & 0 \end{bmatrix}$$

$$q = \begin{bmatrix} 0 & c \\ \bar{c} & 0 \end{bmatrix}$$

~~$$\begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix}, \begin{bmatrix} 0 & c \\ \bar{c} & 0 \end{bmatrix} = \begin{bmatrix} b\bar{c} \\ \bar{b}c \end{bmatrix}$$~~

$$\begin{bmatrix} 0 & c \\ \bar{c} & 0 \end{bmatrix} \begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix}, \begin{bmatrix} 0 & c \\ \bar{c} & 0 \end{bmatrix} = \begin{bmatrix} b\bar{c} - c\bar{b} & 0 \\ 0 & \bar{b}c - c\bar{b} \end{bmatrix}$$

want  $b_0\bar{c} - c\bar{b}_0 = b_0\bar{c} - cb_0$ 

~~$$\begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix}, \begin{bmatrix} 0 & c \\ \bar{c} & 0 \end{bmatrix} = \begin{bmatrix} b\bar{c} \\ \bar{b}c \end{bmatrix}$$~~

$$K = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

$$b_0\bar{c} - cb_0 \quad \begin{bmatrix} K & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \bar{A} & \bar{B} \\ \bar{C} & \bar{D} \end{bmatrix} - \begin{bmatrix} A & B \\ C & D \end{bmatrix} \begin{bmatrix} K & 0 \\ 0 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} K\bar{A} & K\bar{B} \\ 0 & 0 \end{bmatrix} - \begin{bmatrix} AK & 0 \\ CK & 0 \end{bmatrix}$$

$$= \begin{bmatrix} K\bar{A} - AK & K\bar{B} \\ -CK & 0 \end{bmatrix}$$

You want  $b_0\bar{c} - cb_0 = 0$   
 This means  $B=0, C=0$   
 and that  $K\bar{A} = AK$

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Recall that  $c = \begin{bmatrix} A & B \\ C & D \end{bmatrix}$  sat  $c^t = -c$

so  $A^t = -A, D^t = -D$   $A = \begin{bmatrix} 0 & x \\ -x & 0 \end{bmatrix}$

$$\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} 0 & \bar{x} \\ -\bar{x} & 0 \end{bmatrix} - \begin{bmatrix} 0 & x \\ -x & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} -\bar{x} & 0 \\ 0 & -\bar{x} \end{bmatrix} - \begin{bmatrix} -x & 0 \\ 0 & -x \end{bmatrix} = \begin{bmatrix} x-\bar{x} & 0 \\ 0 & x-\bar{x} \end{bmatrix} \quad \text{i.e. } x \text{ real}$$

Repeat this.  $L_{SO(2n)} = \left\{ \begin{bmatrix} a & b \\ \bar{b} & \bar{a} \end{bmatrix} : \begin{matrix} a^t = -a \\ b^t = -b \end{matrix} \right\}$

Let  $b_0 = \left[ \begin{array}{c|c} \begin{matrix} 0 & 1 \\ -1 & 0 \end{matrix} & \begin{matrix} 0 \\ \vdots \\ 0 \end{matrix} \\ \hline \begin{matrix} 0 \\ \vdots \\ 0 \end{matrix} & \begin{matrix} 0 \\ \vdots \\ 0 \end{matrix} \end{array} \right]$

$\xrightarrow{2} \quad \xleftarrow{n-2}$

$$p_0 = \left[ \begin{array}{c|c} \begin{matrix} 1 \\ \vdots \\ 1 \end{matrix} & \begin{matrix} b_0 \\ \vdots \\ b_0 \end{matrix} \\ \hline \begin{matrix} \bar{1} \\ \vdots \\ \bar{1} \end{matrix} & \begin{matrix} c \\ \vdots \\ c \end{matrix} \end{array} \right] \quad p = \left[ \begin{array}{c|c} \begin{matrix} 1 \\ \vdots \\ 1 \end{matrix} & \begin{matrix} c \\ \vdots \\ c \end{matrix} \\ \hline \begin{matrix} \bar{1} \\ \vdots \\ \bar{1} \end{matrix} & \begin{matrix} c \\ \vdots \\ c \end{matrix} \end{array} \right]$$

$$c = \left[ \begin{array}{c|c} \begin{matrix} q & r \\ \hline s & t \end{matrix} & \begin{matrix} r \\ \hline t \end{matrix} \end{array} \right]$$

$$\begin{matrix} c^t = -c \\ q^t = -q, r^t = -r \\ s^t = -s, t^t = -t \end{matrix}$$

$$\therefore q = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

When ~~do~~  $p$  and  $p_0$  commute?

~~$[p_0, p]$~~   $\left[ \begin{array}{c|c} \begin{matrix} 1 \\ \vdots \\ 1 \end{matrix} & \begin{matrix} b_0 \\ \vdots \\ b_0 \end{matrix} \\ \hline \begin{matrix} \bar{1} \\ \vdots \\ \bar{1} \end{matrix} & \begin{matrix} c \\ \vdots \\ c \end{matrix} \end{array} \right] \left[ \begin{array}{c|c} \begin{matrix} 1 \\ \vdots \\ 1 \end{matrix} & \begin{matrix} b_0 \\ \vdots \\ b_0 \end{matrix} \\ \hline \begin{matrix} \bar{1} \\ \vdots \\ \bar{1} \end{matrix} & \begin{matrix} c \\ \vdots \\ c \end{matrix} \end{array} \right]$

$$[p_0, p] = \begin{bmatrix} b_0 \bar{c} & \\ & \bar{b}_0 c \end{bmatrix} - \begin{bmatrix} c \bar{b}_0 & \\ & \bar{c} b_0 \end{bmatrix} = \begin{bmatrix} b_0 \bar{c} - c \bar{b}_0 & 0 \\ 0 & \bar{b}_0 c - \bar{c} b_0 \end{bmatrix}$$

Ans. when  $b_0 \bar{c} = c \bar{b}_0$

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$$b_0 = \left[ \begin{array}{c|c} J & 0 \\ \hline 0 & 0 \end{array} \right]$$

$$c = \left[ \begin{array}{c|c} g & r \\ \hline s & l \end{array} \right]$$

$$b_0 \bar{c} = \left[ \begin{array}{c|c} J\bar{g} & J\bar{r} \\ \hline 0 & 0 \end{array} \right]$$

$$c^T b_0 = \left[ \begin{array}{c|c} g^T J & 0 \\ \hline s^T J & 0 \end{array} \right]$$

so  $b_0 \bar{c} - c^T b_0 = \left[ \begin{array}{c|c} J\bar{g} - g^T J & J\bar{r} \\ \hline -s^T J & 0 \end{array} \right]$

$$J \bar{g} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} 0 & \lambda \\ -\lambda & 0 \end{bmatrix} = \begin{bmatrix} -\lambda & 0 \\ 0 & -\lambda \end{bmatrix}$$

$$\begin{bmatrix} 0 & \lambda \\ -\lambda & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} = \begin{bmatrix} \lambda & 0 \\ 0 & -\lambda \end{bmatrix}$$

$\therefore [p_0, p] = 0 \iff r=0, s=0, g = \begin{bmatrix} 0 & \lambda \\ -\lambda & 0 \end{bmatrix} : \lambda \in \mathbb{R}$

$\{p : [p_0, p] = 0\} = \left\{ \left[ \begin{array}{c|c} \bar{c} & c \end{array} \right] : c = \begin{bmatrix} g & 0 \\ 0 & l \end{bmatrix} \right\}$   $l^t = -l$

You would like next to really understand how the above calculation leads ~~to~~ inductively to eigenvalues. You start with  $U(n)$  acting on <sup>complex skew-</sup>symmetric  $n \times n$  matrices:  $u \# b = ubu^t$ ,

but maybe better notation:  $\begin{bmatrix} u & 0 \\ 0 & \bar{u} \end{bmatrix} \begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix} \begin{bmatrix} u^* & 0 \\ 0 & u^t \end{bmatrix} = \begin{bmatrix} 0 & ubu^t \\ \bar{u}b\bar{u}^* & 0 \end{bmatrix}$

Your aim is to find ~~an~~ ~~orthonormal basis of~~  $\mathbb{C}^n$  ~~such that~~  $u \in U(n)$  such that  $ubu^t$  is diagonal with  $\lambda \geq 0$ .

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Return to  $LSp(2n) = k \oplus \mathfrak{p}$

$$k = \left\{ \begin{bmatrix} a & 0 \\ 0 & \bar{a} \end{bmatrix} : a^* = -a \right\}, \quad \mathfrak{p} = \left\{ \begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix} : b^t = b \right\}$$

$$b_0 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \quad \begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix} \begin{bmatrix} 0 & c \\ -\bar{c} & 0 \end{bmatrix} \begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix} = \begin{bmatrix} -\bar{c}b + b\bar{c} & \\ & \bar{b}c - \bar{c}b \end{bmatrix}$$

Find when  $p = \begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix}$  centralizes  $p_0 = \begin{bmatrix} 0 & b_0 \\ -b_0 & 0 \end{bmatrix}$

$$c = \begin{bmatrix} q & r \\ s & l \end{bmatrix} \quad b\bar{c} - c\bar{b} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \bar{q} & \bar{r} \\ \bar{s} & \bar{l} \end{bmatrix} = \begin{bmatrix} \bar{q} & \bar{r} \\ 0 & 0 \end{bmatrix}$$

$$- \begin{bmatrix} q & r \\ s & l \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} q & 0 \\ s & 0 \end{bmatrix}$$

$$b\bar{c} - c\bar{b} = \begin{bmatrix} \bar{q} - q & \bar{r} \\ -s & 0 \end{bmatrix} = 0 \iff q \in \mathbb{R}, r=0, s=0.$$

centralizer of  $p_0 = \left\{ c = \begin{bmatrix} \mathbb{R} & 0 \\ 0 & \text{Symm}_{n-1 \times n-1} \end{bmatrix} \right\}$

Discuss the situation. You have made some progress on the idea of splitting off one line. Start earlier. You are studying a complex v.s. V with pos herm. form together with a symmetric form,

~~equivalently you want~~

to study the action of  $u \in U(n)$  on complex symmetric matrices  $b$  given by  $u \# b = ubu^t$ . Special

case  $b = \begin{bmatrix} 1 & & & \\ & 0 & & \\ & & 0 & \\ & & & 0 \end{bmatrix}$

~~equivalently you want~~

$$b = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} [1 \ 0 \ 0 \ 0] \quad ubu^t = u \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} [1 \ 0 \ 0 \ 0] u^t$$

is  $VV^t$  where  $V$  is a unit vector

$$= \begin{bmatrix} u_{11} \\ \vdots \\ u_{1n} \end{bmatrix} [u_{11} \ \dots \ u_{1n}]$$

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Repeat: You have  $u \in U(n)$  acting on complex symm. b by  $u \# b = ubu^t$ . Better you have a complex v.s.  $V$  equipped with a pos herm. form and a  $\mathbb{C}$  bilinear symm. form.

You want to find a line  $l \subset V$  such that  $l$  and  $l^\perp$  are orthogonal with respect to the symmetric bilinear form.

$l$  is generated by a unit vector, unique up to mult. by  $\mathbb{T}$ .

Idea today, Apr 9 is to go back to a complex ~~vector space~~ vector space equipped with a symplectic structure and also a pos hermitian form. You recall trying to construct a ~~canonical form~~ canonical form for such a situation.

Begin with  $n=1$  i.e.  $\dim_{\mathbb{C}} V = 2$ . Pick a line  $l$ , then you get a  $\perp$  line  $l^\perp$ , and the symplectic form gives you a canon isom  $l \otimes l^\perp \xrightarrow{\sim} \mathbb{C}$ . There should be an invariant  $\lambda > 0$  here. Choose unit vectors in  $l$  and  $l^\perp$ .

$\dim_{\mathbb{C}} V = 2$ .  $V$  equipped with (pos herm form, symplectic " )

$l$  line in  $V$ ,  $l^\perp$   $l \hookrightarrow V \twoheadrightarrow l^\perp$

have canon isom:  $\Lambda^2 V \xrightarrow{\sim} l \otimes l^\perp$

have  $\Lambda^2 V \xrightarrow{\sim} \mathbb{C}$  given by the symplectic form.

Choose unit vectors  $v, w$  in  $l$  and  $l^\perp$ . Then

$\omega(v, w) \in \mathbb{C}^\times$ . Arbitrariness of phases in  $v, w$  yields positive  $\lambda, > 0$  as invariant



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 first unit vectors be  $\begin{bmatrix} p \\ q \end{bmatrix}$ ,  $\begin{bmatrix} r \\ s \end{bmatrix}$  so that  
 + second

one has  $|p|^2 + |q|^2 = 1 = |r|^2 + |s|^2$ ,  $\overline{p}r + \overline{q}s = 0$ .

$$\begin{bmatrix} p & -\overline{q} \\ q & +\overline{p} \end{bmatrix} = \begin{bmatrix} p & r \\ -\overline{r} & \overline{p} \end{bmatrix}$$

~~Review~~ Review.  $V$  2dim  $\mathbb{C}$  with pos herm. form  
 and symplectic form  $\Lambda^2 V \xrightarrow{\sim} \mathbb{C}$ . You pick a  
 line  $l \subset V$ , let  $l^\perp \subset V$  be the orthogonal line,  
 then get  $l \otimes l^\perp \xrightarrow{\sim} \Lambda^2 V$  via  $\iota$  followed by  
 $\Lambda^2 V \xrightarrow{\sim} \mathbb{C}$ . If you pick unit vectors  
 $x \in l$ ,  $y \in l^\perp$  then  $x \wedge y \mapsto \omega(x, y)$  is determined  
 up to  $\mathbb{T}$  factors  $\therefore$  get inv.  $|\omega(x, y)|$

Example  $V = \mathbb{C}^2$  with standard  $x^* y$   
 and symplectic form  $\lambda \begin{vmatrix} x_1 & y_1 \\ x_2 & y_2 \end{vmatrix} = \lambda \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}^t \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$

There's confusion about the problem. This arose  
 because you want a "flag" approach to symplectic  
 structures under unitary equivalence, and you think  
 there's ~~some~~ a similarity with with the  
 orbit structure of  $U(n)$  acting on complex symmetric  
 $n \times n$  matrices via ~~the~~  $u * b = ubu^t$ . This

seems reasonable but you have to be careful. First  
 check that  $\begin{bmatrix} 0 & b \\ -\overline{b} & 0 \end{bmatrix}$  is skew hermitian  $b^* = \overline{(b^t)} = \overline{b}$

~~the~~  $\begin{bmatrix} 0 & b \\ c & 0 \end{bmatrix}^* = \begin{bmatrix} 0 & c^* \\ b^* & 0 \end{bmatrix} = \begin{bmatrix} 0 & \overline{c} \\ \overline{b} & 0 \end{bmatrix}$  If  $c = -\overline{b}$ , then  
 $\overline{c} = -b$  so OK

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$$\begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix}^* = \begin{bmatrix} 0 & -(b)^* \\ \bar{b}^* & 0 \end{bmatrix} = \begin{bmatrix} 0 & -b^t \\ \bar{b} & 0 \end{bmatrix} = \begin{bmatrix} 0 & -b \\ \bar{b} & 0 \end{bmatrix}$$

Similarly if  $b^t = -b$ , then

$$\begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix}^* = \begin{bmatrix} 0 & \bar{b}^* \\ b^* & 0 \end{bmatrix} = \begin{bmatrix} 0 & b^t \\ \bar{b} & 0 \end{bmatrix} = \begin{bmatrix} 0 & -b \\ -\bar{b} & 0 \end{bmatrix}$$

~~Thus  $\omega$  is a symplectic form. Let's check  $\omega$  is~~

Repeat: ~~check  $\omega$  is~~ Problem. Given a complex vector space  $V$  with  $\omega$  pos herm form  $\omega$  symplectic form. To classify these.

$\dim V = 2$ . Pick  $l$  get  $l \oplus l^\perp = V$   
 and  $l \otimes l^\perp = \Lambda^2 V \xrightarrow{\omega} \mathbb{C}$

Better: Pick a unit vector  $v$

$\dim V = 2$  inner product  $x^*y$ , symplectic form  $\omega$   
 $x^t \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} y$  change orthonormal basis  $U \begin{bmatrix} 0 & \lambda \\ -\lambda & 0 \end{bmatrix} U^t$

$$u = \begin{bmatrix} a & b \\ -\bar{b} & \bar{a} \end{bmatrix} \begin{bmatrix} e^{i\theta} & 0 \\ 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} a & b \\ -\bar{b} & \bar{a} \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} a & -\bar{b} \\ b & \bar{a} \end{bmatrix}$$

$$= \begin{bmatrix} -b & a \\ -\bar{a} & -\bar{b} \end{bmatrix} \begin{bmatrix} a & -\bar{b} \\ b & \bar{a} \end{bmatrix}$$

~~$$\begin{bmatrix} a & -\bar{b} \\ b & \bar{a} \end{bmatrix} \begin{bmatrix} a & -\bar{b} \\ b & \bar{a} \end{bmatrix} = \begin{bmatrix} |a|^2 & a\bar{a} - b\bar{b} \\ a\bar{a} - b\bar{b} & |b|^2 \end{bmatrix}$$~~

$$= \begin{bmatrix} 0 & |a|^2 + |b|^2 \\ -|a|^2 - |b|^2 & 0 \end{bmatrix}$$

$$\begin{bmatrix} e^{i\theta} & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} e^{+i\theta} & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & e^{2i\theta} \\ -e^{2i\theta} & 0 \end{bmatrix}$$

$$g^t \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} g = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

$\det g = 1$ , no condition on  $g$ :

$$\begin{bmatrix} a & c \\ b & d \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} -c & a \\ -d & b \end{bmatrix} \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} a & c \\ b & d \end{bmatrix}$$

original approach: Pick unit vector  $\begin{bmatrix} x \\ y \end{bmatrix}$  then  $\begin{bmatrix} -\bar{y} \\ x \end{bmatrix}$  is a  $\perp$  unit vector so  $\begin{bmatrix} x & -\bar{y} \\ y & x \end{bmatrix} \in SU(2)$ . nice choice of orth basis

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symplectic form ~~is~~ applied to  $\begin{bmatrix} x \\ y \end{bmatrix} \begin{bmatrix} -\bar{y} \\ \bar{x} \end{bmatrix}$

$$\text{is } \begin{bmatrix} x & y \end{bmatrix}^t \begin{bmatrix} 0 & 1 \\ -\lambda & 0 \end{bmatrix} \begin{bmatrix} -\bar{y} \\ \bar{x} \end{bmatrix} = \lambda(|x|^2 + |y|^2) = \lambda$$

Aim?  $V = \mathbb{C}^2$  with  $\|v\|^2$  and  $v_1, v_2$

Your aim is to classify ~~symmetric bilinear~~ <sup>symplectic</sup> forms under unitary equivalence. When  $n=2$  the symplectic forms

are  $\{ \lambda \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} : \lambda \in \mathbb{C} \}$ . A general unitary transf. is the product of an ~~...~~  $\begin{bmatrix} a & b \\ -\bar{b} & \bar{a} \end{bmatrix}$  ( $|a|^2 + |b|^2 = 1$ ) and  $\begin{bmatrix} e^{i\theta} & 0 \\ 0 & 1 \end{bmatrix}$

Since  $\{ \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \}$  is a 1-dim repn of  $U(2)$ ,  $SU(2)$  must act trivially.  $\begin{bmatrix} e^{i\theta} & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & \lambda \\ -\lambda & 0 \end{bmatrix} \begin{bmatrix} e^{i\theta} & 0 \\ 0 & 1 \end{bmatrix} = e^{2i\theta} \begin{bmatrix} 0 & \lambda \\ -\lambda & 0 \end{bmatrix}$

So the classification is clear i.e.  $|\lambda| \geq 0$  is the invariant. ~~...~~ NEXT you want  $\dim V = 4$ , that is,

to classify symplectic forms on  $\mathbb{C}^4 = V$  under the action of  $U(4)$ . Try ~~...~~ choosing a symplectic flag. Choose a line in  $V$  and a line orthogonal to the annihilator of  $\ell$

$n=1$ . Choose ~~...~~ unit vector  $\begin{bmatrix} x \\ y \end{bmatrix}$  then extend to  $\begin{bmatrix} x & -\bar{y} \\ y & \bar{x} \end{bmatrix} \in SU(2)$ , then apply symplectic form

which should be  $\begin{bmatrix} x & y \end{bmatrix}^t \begin{bmatrix} 0 & \lambda \\ -\lambda & 0 \end{bmatrix} \begin{bmatrix} -\bar{y} \\ \bar{x} \end{bmatrix} = \lambda(|x|^2 + |y|^2)$

$$\lambda \begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} \bar{x} \\ \bar{y} \end{bmatrix} = \lambda(|x|^2 + |y|^2) = \lambda$$

$$\begin{bmatrix} x & -\bar{y} \\ y & \bar{x} \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} x & y \\ -\bar{y} & \bar{x} \end{bmatrix} = \begin{bmatrix} x & -\bar{y} \\ y & \bar{x} \end{bmatrix} \begin{bmatrix} -\bar{y} & \bar{x} \\ -x & -y \end{bmatrix} = \begin{bmatrix} 0 & |x|^2 + |y|^2 \\ -|y|^2 - |x|^2 & 0 \end{bmatrix}$$

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so now what to do?  $n=2$ . You want to try something similar, namely, you choose a line (which is isotropic)  $l$ , then choose a line  $l' \perp$  annihilator of  $l$ , ~~and~~ choose unit vectors  $v, v'$  in  $l, l'$  resp, ~~and~~ and adjust the phase ~~of  $v'$  say~~ so that  $\omega(v \wedge v') > 0$ .

What do you know? Ignoring the inner product ~~you~~ you can study a symplectic form by choosing a "symplectic flag" namely, you choose a line  $F_1 \subset V$ , pass to  $F_1^\circ/F_1$  the symp quot., then choose a line  $F_2/F_1 \subset F_1^\circ/F_1$  pass to the symp quot  $F_2^\circ/F_2$  etc. It seems you get  $0 < F_1 < F_2 < \dots < F_n = F_n^\circ < F_{n-1}^\circ < \dots < F_1^\circ < V$

~~for  $n=2$~~   $n=2$ . ~~Let's start with  $\mathbb{C}^4 = V$~~  Let's start with  $\mathbb{C}^4 = V$

Go back over what you can det in symmetric space situation: where  $U(n)$  acts on  $n$  complex symmetric and skew symmetric matrices. Take symm. matrices, the case of  $Sp(2n) = \left\{ \begin{bmatrix} a & b \\ -\bar{b} & \bar{a} \end{bmatrix} : \begin{matrix} a^* = -a \\ b^t = +b \end{matrix} \right\}$ .

$X = \begin{bmatrix} a & 0 \\ 0 & \bar{a} \end{bmatrix}$      $Y = \begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix}$      $Z = \begin{bmatrix} 0 & c \\ -\bar{c} & 0 \end{bmatrix}$      $b, c$  symm.

~~Let's compute  $[Y, Z]$~~   $[Y, Z] = \begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix} \begin{bmatrix} 0 & c \\ -\bar{c} & 0 \end{bmatrix} - \begin{bmatrix} 0 & c \\ -\bar{c} & 0 \end{bmatrix} \begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix}$   
 $= \begin{bmatrix} -b\bar{c} & 0 \\ 0 & -\bar{b}c \end{bmatrix} - \begin{bmatrix} -cb & 0 \\ 0 & -\bar{c}b \end{bmatrix} = \begin{bmatrix} -b\bar{c} + cb & 0 \\ 0 & -\bar{b}c + \bar{c}b \end{bmatrix}$   
 $(-b\bar{c} + cb)^* = b^t c^* - c^t b^* = b\bar{c} - c\bar{b}$

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$$b = b_0 = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & & & \\ \vdots & & & \\ 0 & & & 0 \end{bmatrix}$$

$$c = [c_{ij}] \text{ (symm.)}$$

$$-b_0 \bar{c} + c \bar{b}_0 = - \begin{bmatrix} \bar{c}_{11} & \dots & \bar{c}_{1n} \\ \vdots & & \vdots \\ 0 & & 0 \end{bmatrix} + \begin{bmatrix} c_{11} & & \\ \vdots & & \\ c_{n1} & & 0 \end{bmatrix} \text{ OK}$$

$$= \begin{bmatrix} c_{11} - \bar{c}_{11} & -\bar{c}_{12} & \dots & -\bar{c}_{1n} \\ c_{21} & & & \\ \vdots & & & \\ c_{n1} & & & 0 \end{bmatrix}$$

vanishes when  $c_{11} = \bar{c}_{11}$   
 $c_{21}, \dots, c_{n1} = 0$   
 $\bar{c}_{12}, \dots, \bar{c}_{1n} = 0$

This calculation is used to get

centralizer of  $b_0$  is

$$\left\{ C = \begin{bmatrix} \mathbb{R} & 0 \\ 0 & \begin{matrix} (n-1) \times (n-1) \\ \text{symmetric} \end{matrix} \end{bmatrix} \right\}$$

Somehow this is the right calculation

Recall existence of ~~eigenvectors~~ <sup>eigenvectors</sup> for hermitian matrices.

$V = \mathbb{C}^n$  let  $x \in V$   $\|x\|=1$ , then

$$x x^* \quad \frac{1}{2} \text{tr}(x x^* A) = \frac{1}{2} x^* A x \quad \text{real fu.}$$

on  $\mathbb{P}\mathbb{C}^n$   $x^* \delta x = 0$  i.e.  $\delta x \perp x$

$$\text{st. } x \in \mathbb{C} \text{ stationary} \Rightarrow \frac{1}{2}(\delta x^* A x + x^* A \delta x) = (\delta x)^* A x = 0$$

$$\text{for all } \delta x \perp x \Rightarrow Ax \in \mathbb{C}x$$

Let's go over the calculations until they become clear. Your starting point should be the conjugacy theorem for  $U(n)$  acting on complex symmetric matrices, eventually skew symm. ones.

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be where next? You want to handle  $U(n)$  and <sup>complex</sup> skew symmetric bilinear forms.

~~skew symmetric~~  $L: SO(2n) = \mathbb{R} \oplus \mathfrak{p}$   $\begin{bmatrix} a & \\ & \bar{a} \end{bmatrix}, \begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix} = \rho$

You want the conjugacy then  $K = \left\{ \begin{bmatrix} u & \\ & \bar{u} \end{bmatrix} : u \in U(n) \right\}$

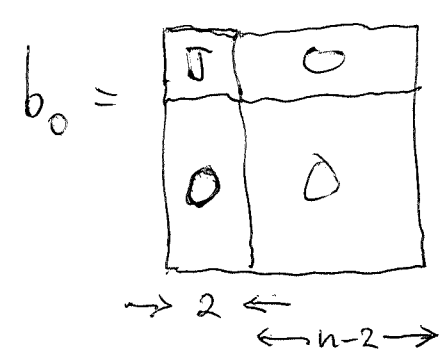
$\frac{1}{2} \text{tr}(kpk^{-1} - p_0)^2 = \frac{1}{2} \text{tr}(p^2 + p_0^2) - \text{tr}(kpk^{-1}p_0)$

$k + \delta k = (1 + X)k$   $X = \begin{bmatrix} a & 0 \\ 0 & \bar{a} \end{bmatrix}$

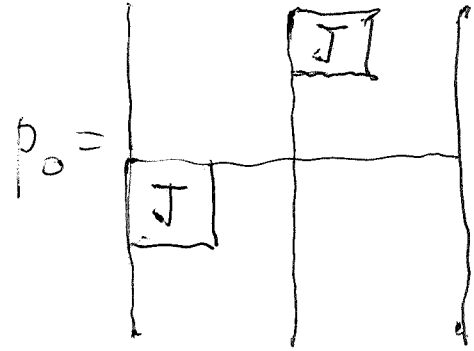
$\delta \text{tr}((1+X)kpk^{-1}(1-X)p_0 - kpk^{-1}p_0)$

$0 = \text{tr}([X, kpk^{-1}]p_0) = \text{tr}(X, [kpk^{-1}, p_0])$

$p = \begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix}$   $b^t = -b$   $p_0 = \begin{bmatrix} 0 & b_0 \\ \bar{b}_0 & 0 \end{bmatrix}$



$J = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$



Your linear functional is  $\text{tr}(pp_0)$

$\delta \text{tr}(pp_0) = \text{tr}([X, p]p_0) = \text{tr}(X[p, p_0])$

~~scribbled out text~~

$\left[ \begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix}, \begin{bmatrix} 0 & c \\ \bar{c} & 0 \end{bmatrix} \right] = \begin{bmatrix} b\bar{c} - c\bar{b} & 0 \\ 0 & \bar{b}c - \bar{c}b \end{bmatrix}$

$\text{tr} \left( \begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix} \begin{bmatrix} 0 & c \\ \bar{c} & 0 \end{bmatrix} \right) = \text{tr}(b\bar{c} + \bar{b}c)$

(219) Repeat with the aim of making the inductive step clear. It should be possible to do everything in half the degree.

Let's begin with  $V$ , ~~equipped with~~ a finite dim complex Hilbert space equipped with symmetric bilinear form. ~~As a model~~ Your model should be  $u \in U(n)$  acting on  $b$  symmetric via  $u b u^t$ . You have this simple picture. The obvious thing to try for? At the moment you have a specific conjugacy class in  $Sp(2n)$  (or  $SO(2n)$ )

$$\begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix}: b^t = b \qquad \begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix}: b^t = -b$$

How to tell: you want  $\begin{bmatrix} 0 & b \\ \bar{b} & 0 \end{bmatrix}$  to be skew-symm. i.e.  $-b^* = \bar{b}$  a.e.  $-b^t = b$ . You can also keep them straight because  $Sp(2n)$  has larger dim.

What might be significant about  $b_0 = \begin{bmatrix} 1 & n \\ \bar{1} & s \end{bmatrix}$

This is supposed to be symmetric:  $s^t = s$ , ~~and~~  $g^t = n$

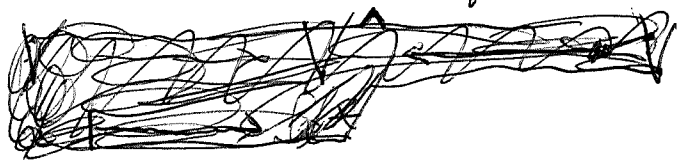
$$\text{tr} \left( \begin{bmatrix} 0 & b \\ -\bar{b} & 0 \end{bmatrix} \begin{bmatrix} 0 & c \\ -\bar{c} & 0 \end{bmatrix} \right) = \text{tr}(-b\bar{c} - \bar{b}c)$$

Another idea is to use  $\begin{bmatrix} 1 \\ g \end{bmatrix} \begin{bmatrix} 1 & g^t \end{bmatrix}$ . What is the significance of  $P_0 = \begin{bmatrix} 0 & b_0 \\ -\bar{b}_0 & 0 \end{bmatrix}$  as an operator on  $V$

Start again  $V$  complex vis. with pos herm. form and also a ~~complex bilinear~~ symmetric forms. You want an ~~eigenvector~~ picture for these. ~~Simplest method~~ This means an orthonormal basis for  $V$  which diagonalizes the symmetric form.

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Ideas: difference (mult. sense) between the pos. hermitian form and the symmetric bilinear form



$$V \xrightarrow{b} V^{\wedge} \xleftarrow{\sim} V$$

$$x^* \longleftarrow x$$

So it seems that you get an antilinear endo of  $V$ . What sort of symmetry?

Choose  $V = \mathbb{C}^n$  orthonormal basis.

$$\mathbb{C}^n \longleftarrow \mathbb{C}^n \xrightarrow{b_{ij}} \mathbb{C}^n \longleftarrow \mathbb{C}^n$$

$$[\bar{y}_1 \dots \bar{y}_n] \longleftarrow \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} \quad [\bar{x}_1 \dots \bar{x}_n] \longleftarrow \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$$

Let's be more precise.

Begin with inner product  $\langle \sigma_1, \sigma_2 \rangle$  and the symm form  $S(\sigma_1, \sigma_2)$ .  $S: V \rightarrow V^{\wedge}$

$$V \xleftarrow{\sim} \hat{V} \xleftarrow{S} V \xleftarrow{\sim} \hat{V}$$

$$\downarrow \quad \downarrow \quad \downarrow \quad \downarrow$$

$$J \quad -J \quad -J \quad J$$

Apparently this doesn't work because you get an anti-linear map. You can try forgetting the complex structure.

So you ~~assume~~ assume  $V$  is a Euclidean space <sup>(equipped)</sup> with a complex structure  $J$ .  $\hat{V}$  is  $V$  equipped with complex structure  $-J$ . Can you show there's a canonical isom.  $V \xrightarrow{\sim} \hat{V}$ . This should be just the scalar product from the Euclidean structure  $J^t$



(221)  $V$  Euclidean space, there is a canonical isomorphism  $\varphi: V \xrightarrow{\sim} \text{Hom}_{\mathbb{R}}(V, \mathbb{R})$ ,  $J$  complex structure on  $V$ ,  $J$  is orthogonal of square  $-1$ .

$$\varphi(v)(\sigma_1) = (v, \sigma_1)$$

$$(J\sigma, J\sigma_1) = (J^t J \sigma, \sigma_1)$$

$$(v, \sigma_1) \quad \therefore J^t J = 1$$

$$v \in V \xrightarrow{\varphi} \text{Hom}_{\mathbb{R}}(V, \mathbb{R})$$

$$J \downarrow$$

$$\uparrow J^*$$

$$Jv \in V \quad \text{Hom}_{\mathbb{R}}(V, \mathbb{R})$$

$$Jv \mapsto (\sigma_1 \mapsto (Jv, \sigma_1)) = \varphi_{Jv}$$

$V$   $\mathbb{R}$ -vector space with  $(\sigma_1, \sigma_2)$  scalar product.

$W$   $(\omega_1, \omega_2)$

$T: V \rightarrow W$  induces  $T^t: W^\wedge \rightarrow V^\wedge$

$$g \mapsto gT$$

But you have  $\varphi: W \xrightarrow{\sim} W^\wedge$

$$\varphi_\omega(\omega') = (\omega, \omega')$$

$$\varphi_\omega \mapsto \varphi_\omega T$$

$$(\varphi_\omega T)(v) = \varphi_\omega(Tv) = (\omega, Tv)$$

$V$  with  $(v, v')$

$$\varphi: V \rightarrow V^\wedge$$

$$\varphi_v(v') = (v, v')$$

$W$  with  $(\omega, \omega')$

$$\varphi: W \rightarrow W^\wedge$$

$$\varphi_\omega(\omega') = (\omega, \omega')$$

Given  $T: V \rightarrow W$  get

$$T^\wedge: W^\wedge \rightarrow V^\wedge$$

$$T^\wedge g = gT$$

$$(T^\wedge \varphi_\omega)(\omega') = \varphi_\omega(T\omega') = (\omega, T\omega')$$

$$\begin{array}{ccc} \uparrow s & & \uparrow s \\ W & \xrightarrow{\varphi_\omega} & V \\ \varphi_\omega & & T\omega' \end{array}$$

?

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$V$  with  $(\sigma, \sigma')$

$V \xrightarrow{\sim} V^\wedge$

sim  $W$  with  $(\omega, \omega')$

$\sigma \mapsto \varphi_\sigma(\sigma') = (\sigma, \sigma')$

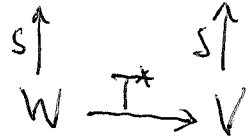
Given  $T: V \rightarrow W$ , get  $T^\wedge: W^\wedge \rightarrow V^\wedge$ ,  $T^\wedge g = gT$

$$(T^\wedge \varphi_\omega)(\sigma') = \varphi_\omega(T\sigma') = (\omega, T\sigma')$$

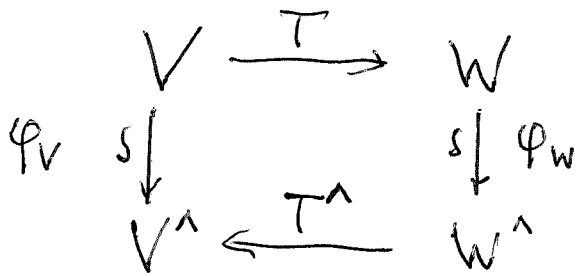
So  $T^\wedge \varphi_\omega \in V^\wedge$  ~~is identified with~~ is  $\varphi_\sigma$

where  $\varphi_\sigma(\sigma') = (\omega, T\sigma')$ . Define  $T^* \omega = \sigma$

Given  $T: V \rightarrow W$ , get  $T^\wedge: W^\wedge \rightarrow V^\wedge$



$$\text{i.e. } (T^* \omega, \sigma') = (\omega, T\sigma')$$

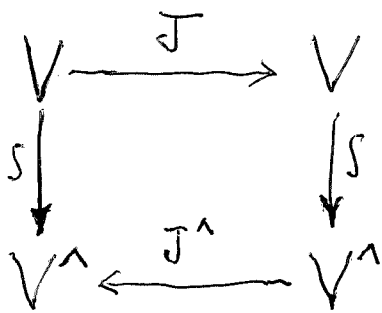


$$T^* = \varphi_V^{-1} T^\wedge \varphi_W$$

$$\varphi_V T^* = T^\wedge \varphi_W = \varphi_W T$$

$$(T^* \omega, \sigma') = (\omega, T\sigma')$$

The next step is when  $W=V$  and  $V$  is equipped with a complex structure  $J$ .



$$J^* = \varphi_V^{-1} J \varphi_V \quad ?$$

The point is that ~~by~~ by defn. a  $J$  is orthogonal:  $J^* = J^{-1}$  & has  $J^2 = -1$ .

~~Use~~ Use Euclidean structure to identify  $V$  with  $\text{Hom}_{\mathbb{R}}(V, \mathbb{R}) = \hat{V}$ , and then you get  $T^t = \varphi_V^{-1} T^\wedge \varphi_W$   
Now  $J$  on  $V$  satisfies  $J^t = J^{-1} = -J$

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$V$  Euclidean with  $J^t = J^{-1} = -J$ . Now you also have  $S: V \rightarrow \text{Hom}(V, \mathbb{C})$  symmetric.  $\text{Hom}_{\mathbb{C}}(V, \mathbb{C}) = \text{Hom}_{\mathbb{R}}(V, \mathbb{R})$

$\text{Hom}_{\mathbb{C}}(V, \text{Hom}_{\mathbb{R}}(\mathbb{C}, \mathbb{R})) = \text{Hom}_{\mathbb{R}}(\mathbb{C} \otimes_{\mathbb{R}} V, \mathbb{R})$

$V$  has symmetric bilinear forms.

You ~~can~~ can try to reduce to  $V$  Euclidean. So far you've reduced  $V$  & hermit inner product to a Euclidean space with  $J$ . Next you want to include a  ~~$\mathbb{C}$ -linear map~~  $S^2 V \rightarrow \mathbb{C}$ . Such a thing is the same as ~~an~~ an  $\mathbb{R}$ -linear  $S^2 V \rightarrow \mathbb{R}$

$V \xrightarrow{S} \hat{V}$

There should be a good way to handle a symmetric form. As

a kind of operator ~~on~~ on  $V$ ? Not ~~obvious~~ obvious because the operator goes from  $V$  to  $\hat{V}$ .

What's your aim? The idea was to start with the symmetric form  $S: V \rightarrow \hat{V}$ .

~~Here  $\hat{V} = \mathbb{R}$ -dual of  $V$ , which you can identify with  $V$ , but equipped with the appropriate  $\mathbb{C}$ -structure.~~ Here  $\hat{V} = \mathbb{R}$ -dual of  $V$ , which you can identify with  $V$ , but equipped with the appropriate  $\mathbb{C}$ -structure.

should amount to a pairing  $V \otimes_{\mathbb{R}} V \rightarrow \mathbb{R}$

with ~~a  $J$~~  appropriate symmetry and  $J$  conditions. What could they be?

$f: V \rightarrow \mathbb{R}$   $\mathbb{R}$ -linear

$\tilde{f}(Jv) = f(Jv) + if(v)$   
 $= i[f(v) - if(Jv)]$   
 $= i\tilde{f}(v)$

$\tilde{f}(v) = f(v) - if(Jv)$

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Now look at a bilinear form  $V \otimes_{\mathbb{C}} V \rightarrow \mathbb{R}$ .  
 $B(v_1, v_2)$ . So you want  $V \xrightarrow{B} \hat{V} \xleftarrow{\sim} V$

$$B: V \otimes_{\mathbb{C}} V \longrightarrow \mathbb{C}$$

$$B(c_1 v_1 + c_2 v_2, d_1 w_1 + d_2 w_2)$$

$$= \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}^t \begin{bmatrix} B(v_1, w_1) & B(v_1, w_2) \\ B(v_2, w_1) & B(v_2, w_2) \end{bmatrix} \begin{bmatrix} d_1 \\ d_2 \end{bmatrix}$$

$$B(cv, dw) = cd B(v, w).$$

$$B((c_1 + c_2 J)v, (d_1 + d_2 J)w)$$

$$= c_1 d_1 B(v, w) + c_1 d_2 B(v, Jw)$$

$$+ c_2 d_1 B(Jv, w) + c_2 d_2 B(Jv, Jw)$$

$$= c_1 d_1 B(v, w) + c_1 d_2 i B(v, w)$$

$$+ c_2 d_1 i B(v, w) + c_2 d_2 i^2 B(v, w)$$

$$= (c_1 d_1 + (c_1 d_2 + c_2 d_1) i - c_2 d_2) B(v, w)$$

So  $\mathbb{C}$ -bilinear means  $B(\lambda v, \mu w) = \lambda \mu B(v, w)$

Reduces conditions

$$B(v, Jw) = B(Jv, w) = i B(v, w)$$

$$B(Jv, Jw) = -B(v, w)$$

(225)  $V$  real Euclidean dim  $2n$  with  $J$   
 have canon. isom  $V \xrightarrow{\sim} \text{Hom}_{\mathbb{C}}(V, \mathbb{C}) \cong \text{Hom}_{\mathbb{R}}(V, \mathbb{R})$ .

Suppose given  $S: V \xrightarrow{\sim} \hat{V}$  symmetric non deg  
 and you combine it with  $\hat{V} \xrightarrow{A^{-1}} \bar{V}$  assoc. to  
 the hermitian inner product. Then you get an  
 anti-linear map  $A^T S: V \rightarrow \bar{V}$  also non deg.

Point eigenvectors makes sense; they are  
 the lines in  $V$  fixed under  $A^T S$ . It should  
 be clear that an anti-linear map ~~on~~  $V$   
 induces a ~~map~~ map on  $PV$ .  $f(cv) = \bar{c}f(v)$ .

Can you say anything about an eigenvalue  
 for an eigenline? This is a 1-dim matter

First define an eigenline <sup>of  $T$</sup>  to be a line  $l \subset V$   
 such that  $T(l) \subset l$ , ~~whence~~ whence  
 $T(l) = l$ . What kind of eigenvalue. Pick  $v_0 \in l$

Then  $T(v_0) = cv_0$  for some  $c \neq 0$ . A  
 different choice of generator  $v_1 = dv_0$  yields

$$\frac{T(v_1)}{v_1} = \frac{\bar{d} T(v_0)}{d v_0} = \frac{\bar{d}}{d} c$$

so  $\left| \frac{T(v_0)}{v_0} \right|$  is independent of the choice of gen.

~~Looks like eigenvalues are~~ a non deg  
 Next look at  $T^2$  which is  $\mathbb{C}$  linear transf  
 on  $V$ . Assume  $T(v_0) = cv_0$ , then  
 $T(T(v_0)) = T(cv_0) = \bar{c}T(v_0) = \bar{c}cv_0$ , so the

226 eigenvalues of  $T^2$  <sup>should be</sup> ~~are~~  $> 0$ . Now you ~~needs the~~ existence.

~~Let  $v$  be an eigenvector of  $T^2$  with eigenvalue  $\mu$ .~~

Let  $T$  be an antilinear transf on  $V$ .  $T(cv) = \bar{c}T(v)$ .

Then  $T^2$  is linear:  $T(T(cv)) = T(\bar{c}T(v)) = cT(T(v))$ .

~~Let  $\mu$  be an eigenvalue of  $T^2$ , put  $V_\mu = \text{Ker}(T^2 - \mu)$ .~~ Let  $\mu$  be an eigenvalue of  $T^2$ , put  $V_\mu = \text{Ker}(T^2 - \mu)$ .  $T^2 v = \mu v$

$\Rightarrow$   ~~$T^2(Tv) = \mu(Tv)$~~

$v \in V_\mu = \text{Ker}(T^2 - \mu)$

$T^2 v = \mu v$

$Tv \in V_{\bar{\mu}} = \text{Ker}(T^2 - \bar{\mu})$

$T^3 v = \bar{\mu}Tv$

$T$  anti-linear transf on  $V$ . ~~Notion of~~ Notion of eigenvector:  $v \neq 0$  s.t.  $Tv = \lambda v$   $\lambda$  scalar.

$T^2 v = T\lambda v = \bar{\lambda}Tv = |\lambda|^2 v$ . ~~Notion of~~

Question: Do the eigenvectors span  $V$ ? ~~Notion of~~

$T$  anti-linear on  $V$ , notion of eigenvector:  $v \neq 0$ ;  $Tv = \lambda v$

Then  $T(Tv) = T(\lambda v) = \bar{\lambda}Tv$  so  $Tv$  is also an eigenvector.

Another point is that the eigenline is the interesting thing. ~~and if~~ and if  $c \neq 0$

then  $T(cv) = \bar{c}Tv = \bar{c}\lambda v$ , so  $\frac{T(cv)}{cv} = \frac{\bar{c}}{c}\lambda = \frac{\bar{c}}{c} \frac{Tv}{v}$

The point is that ~~only~~ only  $|\lambda|$  is determined by the eigenline.

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Now look at  $T^2$  which is linear.

Really you should be doing ~~this~~ this ~~with~~ ~~the~~ ~~structures~~ with Euclidean spaces and complex structures. What does this mean? Ratio of symmetric and hermitian forms.

$$V \xrightarrow{H} \hat{V} \xrightarrow{A^{-1}} V$$

$V$  complex vector space equipped with  $\langle x|y \rangle$  pos herm. form. This should be the same as a Euclidean space together with an operator  $J$  satisfying  $J^t = J^{-1} = -J$  (that is a complex structure)

Problem: ~~Given~~ Given a symmetric complex bilinear form  $S$  on  $V$  (this should be the same as a symmetric real bilinear form on  $V$  ~~satisfying~~ satisfying some compatibility with the operator  $J$ ) you want a "time evolution" associated to  $S$  and the pos. herm form.

Ideas. A complex Hilbert space (= Euclidean space +  $J$ )  from the real viewpoint, has both symmetric  $S$  and skew symmetric forms  $A$ , whose ~~ratio~~ "ratio"  should be  $J$ . Ratio might be understood ~~as~~ as the eigenvalues ~~(better: spectrum)~~ (better: spectrum) of  $A^{-1}S$ .

First task. Make sense of time evolution! There should be some way to do this on the real level.

228 To understand the situation in real terms.

~~The situation:~~ The situation: An  $n$ -dim Hilb space  $V$  equipped with a symmetric bilinear form  $S$ .

Then we have  $V \xrightarrow{S} \hat{V} \xrightarrow{A^{-1}} \bar{V}$  which gives an anti-linear map  $\bar{\cdot}$  on  $V$ . What's the significance of  $S$  being symmetric? Let's do this by introducing coords.  $V = \mathbb{C}^n$  space of column vectors.

$$S: V \rightarrow \hat{V} \text{ is } \sum_j s_{ij} v_j$$

$$\hat{V} \rightarrow \bar{V}$$

$$[y_1, \dots, y_n] \mapsto \begin{bmatrix} \bar{y}_1 \\ \vdots \\ \bar{y}_n \end{bmatrix}$$

Composition ~~combination~~ is

~~$$\sum_j s_{ij} v_j \mapsto \sum_j \bar{v}_j \bar{s}_{ij}$$~~

$$y_i = \sum_j s_{ij} v_j \mapsto \bar{y}_i = \sum_j \bar{s}_{ij} \bar{v}_j = \sum_j \bar{s}_{ij} \bar{v}_j$$

It seems that  $\mathbb{C}^n \xrightarrow{S} \hat{\mathbb{C}}^n \xrightarrow{*} \mathbb{C}^n$

is  $\begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix} \mapsto \begin{bmatrix} s_{1j} v_j \\ \vdots \\ s_{nj} v_j \end{bmatrix} \mapsto \sum_j \bar{s}_{ij} v_j$

So the anti linear map is it seems equal to

$$\begin{bmatrix} v \\ \vdots \\ v \end{bmatrix} \mapsto \sum_j \bar{s}_{ij} \bar{v}_j$$

$$\sum_j s_{ij} v_j \xrightarrow{*} \sum_j \bar{s}_{ij} \bar{v}_j$$

and its square is

$$v \xrightarrow{T} \bar{s} \bar{v} \xrightarrow{T} \bar{s} (\bar{s} \bar{v})$$

~~$$v_k \xrightarrow{T} \bar{s} \bar{v}_k \xrightarrow{T} \bar{s} (\bar{s} \bar{v}_k)$$~~

$$(\bar{s} s)^* = s^* \bar{s}^* = (\bar{s}^t) s^t = \bar{s} s$$

$$(\bar{s} s) v$$